

Nonexistence of k -peak solutions to elliptic problems in convex domains

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The Theorem of Gidas, Ni and Nirenberg (1979)

Let us consider a solution $u \in C^2(\Omega) \cap C(\overline{\Omega})$ of the problem

$$\begin{cases} -\Delta u = f(u) & \text{in } \Omega, \\ u > 0 & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

where $\Omega \subset \mathbf{R}^N$ is a bounded domain which is convex with respect to x_1, \dots, x_N and is symmetric with respect to the planes $x_1 = 0, \dots, x_N = 0$ and f is a locally Lipschitz function.

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Corollary

A consequence of the previous theorem is that 0 is the unique critical point of u .

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$$\sum_{i=1}^N \frac{\partial u}{\partial x_i}(x)(x_i - x_{0,i}) < 0 \quad \text{for any } x \in \Omega \setminus \{x_0\}.$$

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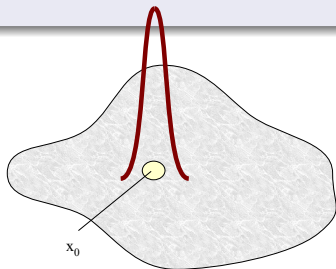
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Conjecture

Let u be a solution of

$$\begin{cases} -\Delta u = u^p & \text{in } \Omega, \\ u > 0 & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

with $1 < p < \frac{N+2}{N-2}$. Then, if Ω is (strictly) convex, the monotonicity property holds.

A brief history on the problem

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Cabré and Chanillo (1998)

Let Ω be a bounded, convex domain of \mathbf{R}^2 where the boundary has positive curvature. Suppose that $f \in C^\infty(\mathbf{R})$, $f \geq 0$ and let u be a semi-stable solution of (i.e. the first eigenvalue of the linearized operator is nonnegative)

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Applications

The previous result applies to the minimal solutions to $f(s) = \lambda e^s$, $\lambda > 0$, and $f(s) = \lambda(1+s)^p$, $\lambda > 0$ and $p > 1$.

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Grossi and Molle (2003)

Let Ω be a bounded, convex domain of \mathbf{R}^N , $N \geq 3$. Let us suppose that u_ϵ is a positive solution of

$$\begin{cases} -\Delta u = u^{\frac{N+2}{N-2}-\epsilon} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

which satisfies (S is the best constant in Sobolev embedding)

$$\frac{\int_{\Omega} |\nabla u_\epsilon|^2}{\left(\int_{\Omega} |u_\epsilon|^{\frac{2N}{N-2}-\epsilon} \right)^{\frac{2(N+2)}{2N+\epsilon(N+2)}}} \rightarrow S$$

Then, denoting by x_ϵ the point where the maximum of u_ϵ is achieved, we have that $(x - x_\epsilon) \cdot \nabla u_\epsilon(x) < 0$ for any $x \in \Omega \setminus \{x_\epsilon\}$, provided ϵ is small enough.

A problem in the plane: the case of one peak

Let us consider the following "model problem",

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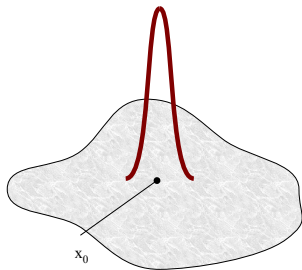
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Theorem

For any $\Omega \subset \mathbb{R}^2$, there exists a solution u_λ with one peak, i.e.

$$u_\lambda(x) \rightarrow G(x, x_0) \quad \text{as } \lambda \rightarrow 0.$$

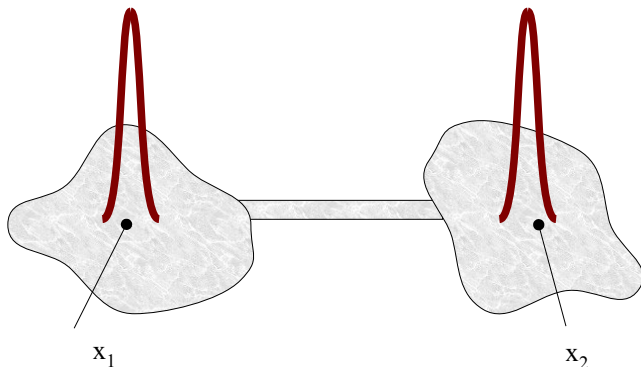


A problem in the plane: the case of k peaks.

According to the shape of the domain, we can have solution with more peaks

Theorem, Esposito, Grossi e Pistoia (2005)

Under some suitable assumptions on $\Omega \subset \mathbf{R}^2$, there exist solution with k peaks, for any $k \geq 2$.



The location of the peaks of the solution has been characterized.

Let us denote by $P_{1,\lambda} \rightarrow P_1, \dots, P_{k,\lambda} \rightarrow P_k$ the peaks of the solution u_λ .

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$$\lambda \int_{\Omega} e^{u_\lambda} \rightarrow 8k\pi \quad \text{as } \lambda \rightarrow 0,$$

then

$$\frac{1}{2} \nabla R(P_i) - \sum_{j=1, j \neq i}^k \nabla_x G(P_i, P_j) = \mathbf{0}$$

Corollary (the case of 2 peaks)

Let us suppose to have a 2-peak solution to

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Then, we have that

$$\lambda \int_{\Omega} e^{u\lambda} \rightarrow 16\pi \quad \text{per } \lambda \rightarrow 0,$$

$$\begin{cases} \frac{1}{2} \nabla R(P_1) = \nabla_x G(P_1, P_2) \\ \frac{1}{2} \nabla R(P_2) = \nabla_x G(P_2, P_1). \end{cases}$$

Theorem, Grossi and Takahashi (2010)

Let Ω be convex and u_λ be a solution of

$$(P_\lambda) \quad \begin{cases} -\Delta u = \lambda e^u & \text{in } \Omega \subset \mathbf{R}^2, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

with $\|u_\lambda\| \rightarrow +\infty$ as $\lambda \rightarrow 0$. Then we have that,

$$\lambda \int_{\Omega} e^{u_\lambda} \rightarrow 8\pi \quad \text{per } \lambda \rightarrow 0.$$

Hence, for λ small enough, all the solutions have just one peak.

Lemma

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$$\int_{\partial\Omega} (x - Q) \cdot \nu(x) \left(\frac{\partial G(x, P_1)}{\partial \nu_x} \right) \left(\frac{\partial G(x, P_2)}{\partial \nu_x} \right) ds_x$$

$$= (2 - N)G(P_1, P_2) + (Q - P_1) \cdot \nabla_x G(P_1, P_2) + (Q - P_2) \cdot \nabla_x G(P_2, P_1)$$

where $Q \in \mathbb{R}^2$ and $\nu(x)$ is the unit outer normal to $x \in \partial\Omega$.

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which satisfies $-\Delta w = (x - Q) \cdot \nabla \delta_{P_1} + 2\delta_{P_1}$.

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Sketch of the proof

Let Ω be convex and u_λ be a solution of

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with $\|u_\lambda\| \rightarrow +\infty$ as $\lambda \rightarrow 0$.

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Sketch of the proof

- **Step1:** boundedness of $\lambda \int e^u$
- **Step2:** nonexistence of k -peak solution with $k \geq 2$ via the integral identity.

Theorem

Let Ω be convex and u_ϵ be a solution of

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Then, for $\epsilon > 0$ small enough, all solutions have just one peak.

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- **Bounds on energy.** In this case the Pohozaev identity seems difficult to use. However, Y.Y. Li (1995) proved that all solutions to (P_ϵ) satisfy the a-priori estimate $\int_{\Omega} |\nabla u_\epsilon|^2 \leq C$.

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- **Location of the peaks.** It is (almost) the same of the two dimensional problem, (Bahri, Li e Rey (1995)).
- **Convexity of the Robin function.** In dimensions $N \geq 3$ the convexity of the Robin function was proved by Cardaliaguet and Tahraoui (2002).

Thank you

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