

TA2 Test Case

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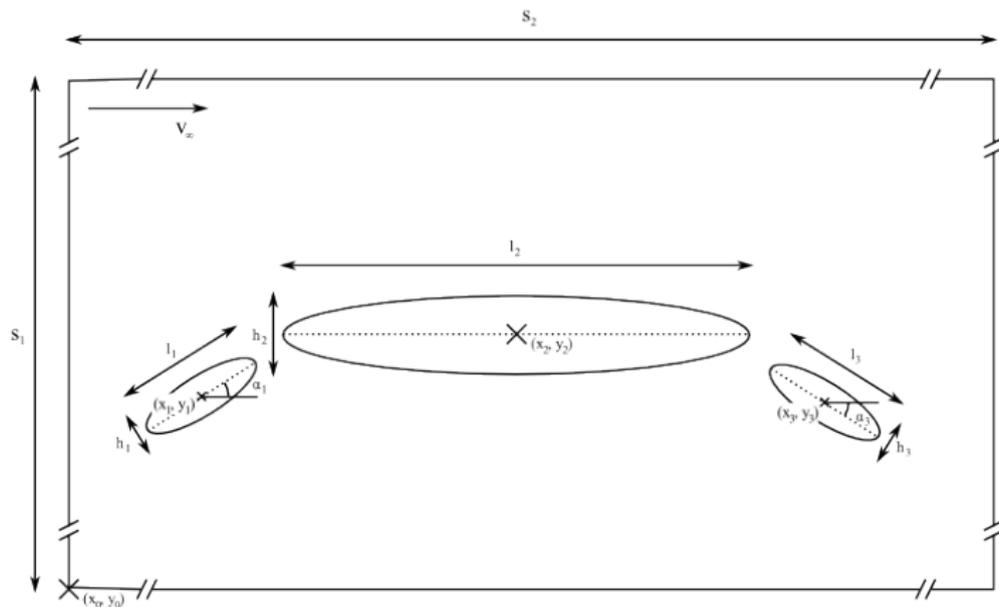
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Integrated Multiphysics Simulation & Design Optimization
Second Database Workshop for multiphysics optimization software
validation
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Aerodynamic reconstruction problem

Recovery of the original position of two ellipses using Navier-Stokes flows for $Re = 100$ and $Re = 500$



TA2 test case: Design variables, bounds, target

Design parameters:

$$\begin{aligned} -10.0 &\leq x_1 \leq -6.5 && \text{position of the ellipse 1} \\ -1.5 &\leq y_1 \leq 0.0 && \\ -10.0^\circ &\leq \alpha_1 \leq 0.0^\circ && \text{clockwise angle of the ellipse 1} \\ 7.25 &\leq x_3 \leq 10.0 && \text{position of the ellipse 3} \\ -1.5 &\leq y_3 \leq 0.0 && \\ 0.0^\circ &\leq \alpha_3 \leq 10.0^\circ && \text{clockwise angle of the ellipse 3} \end{aligned}$$

In addition, the ellipses/ellipsoids must not be overlapping.

Target:

$$\{x_1, y_1, \alpha_1, x_3, y_3, \alpha_3\} = \{-7.0, -0.5, -3.0^\circ, 7.5, -0.5, 3.0^\circ\}$$

TA2 test case: Flow conditions

- Incompressible fluid (Navier-Stokes laminar flow)
Our results are for $M_\infty = 0.2$
- Reynolds number $Re = 100$ or 500
Our results are for $Re = 500$ and 1000
- Angle of attack $\alpha = 5$ deg.

Recovery of position by minimizing the pressure difference

$$\min f = \int_{\Gamma_1} (p_1 - p_1^*)^2 + \int_{\Gamma_2} (p_2 - p_2^*)^2 + \int_{\Gamma_3} (p_3 - p_3^*)^2$$

- Finite volume scheme
- Unstructured, triangular grids
- Roe flux
- MUSCL reconstruction
- Implicit scheme

Source code of flo2d available online
<http://flo2d.googlecode.com>

- x^0 = Design variables corresponding to middle of design space
- G_0 = Grid corresponding to x_0 (Reference grid)
- To obtain grid for any other configuration, we deform the reference grid using Radial Basis Function interpolation.
- Grid points on middle ellipse and outer boundary are fixed
- Grid used in this work
 - ▶ 33438 vertices
 - ▶ 65994 triangles
- Grid generated using delaundo

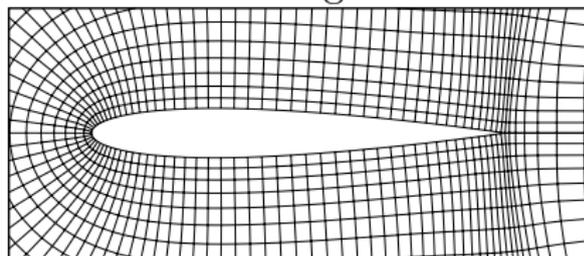
- **Interpolate** displacement of **surface** points to **interior** points using RBF

$$\tilde{f}(x, y) = a_0 + a_1x + a_2y + \sum_{j=1}^N b_j |\vec{r} - \vec{r}_j|^2 \log |\vec{r} - \vec{r}_j|$$

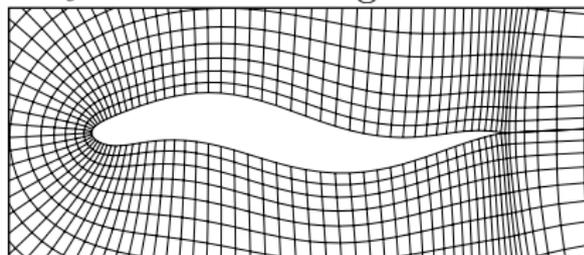
where $\vec{r} = (x, y)$

- Results in **smooth** grids

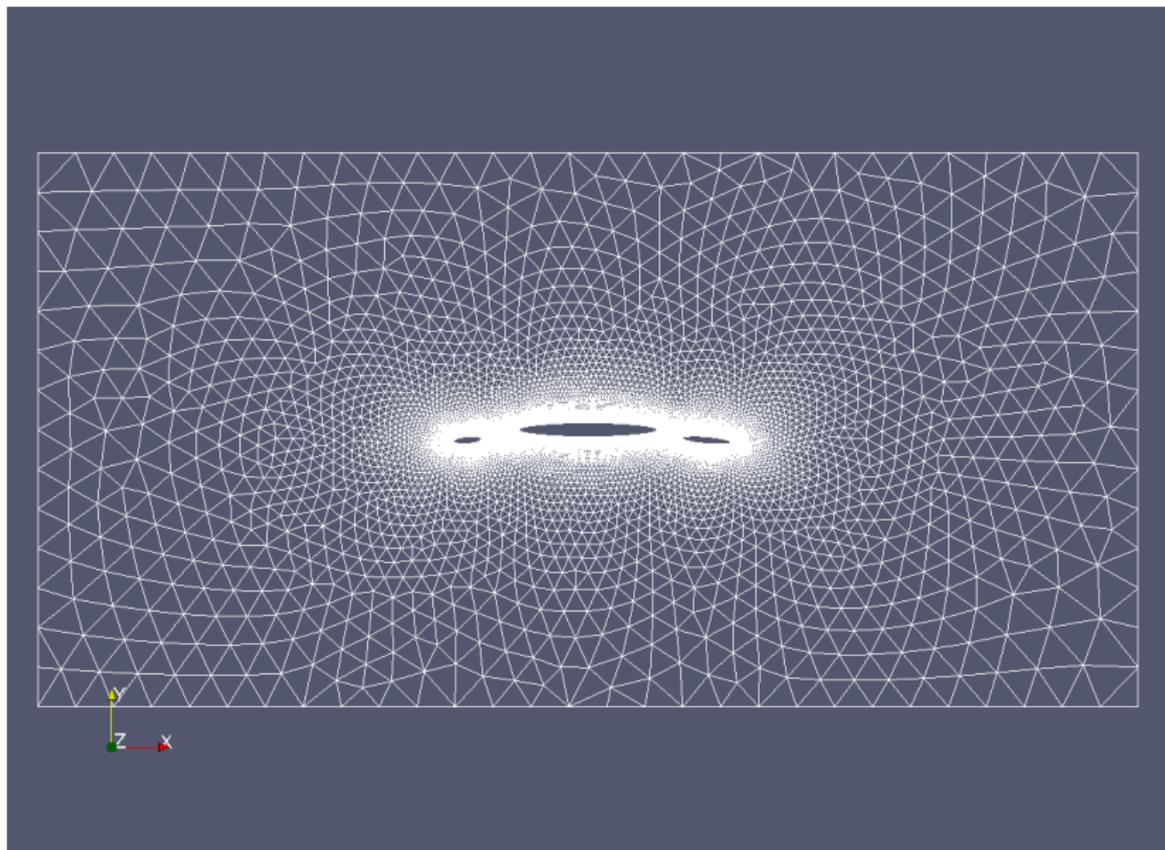
Initial grid



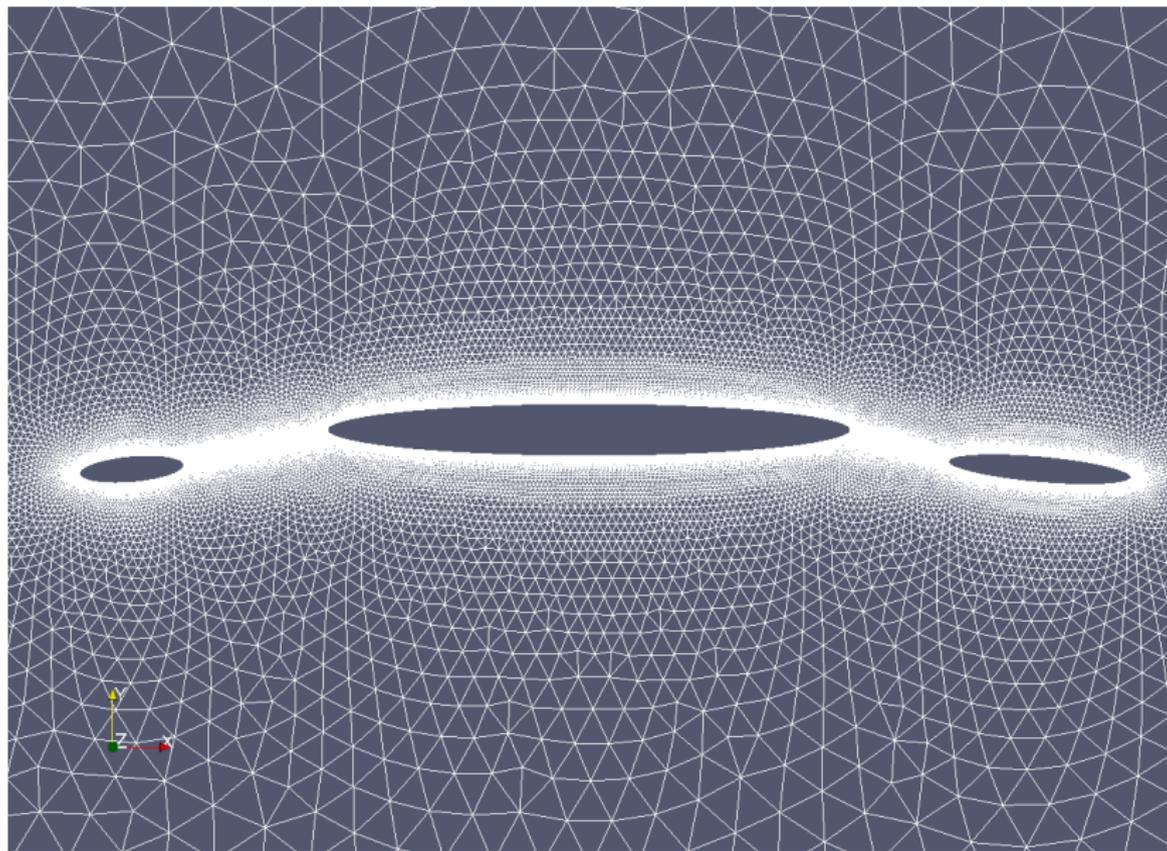
Deformed grid



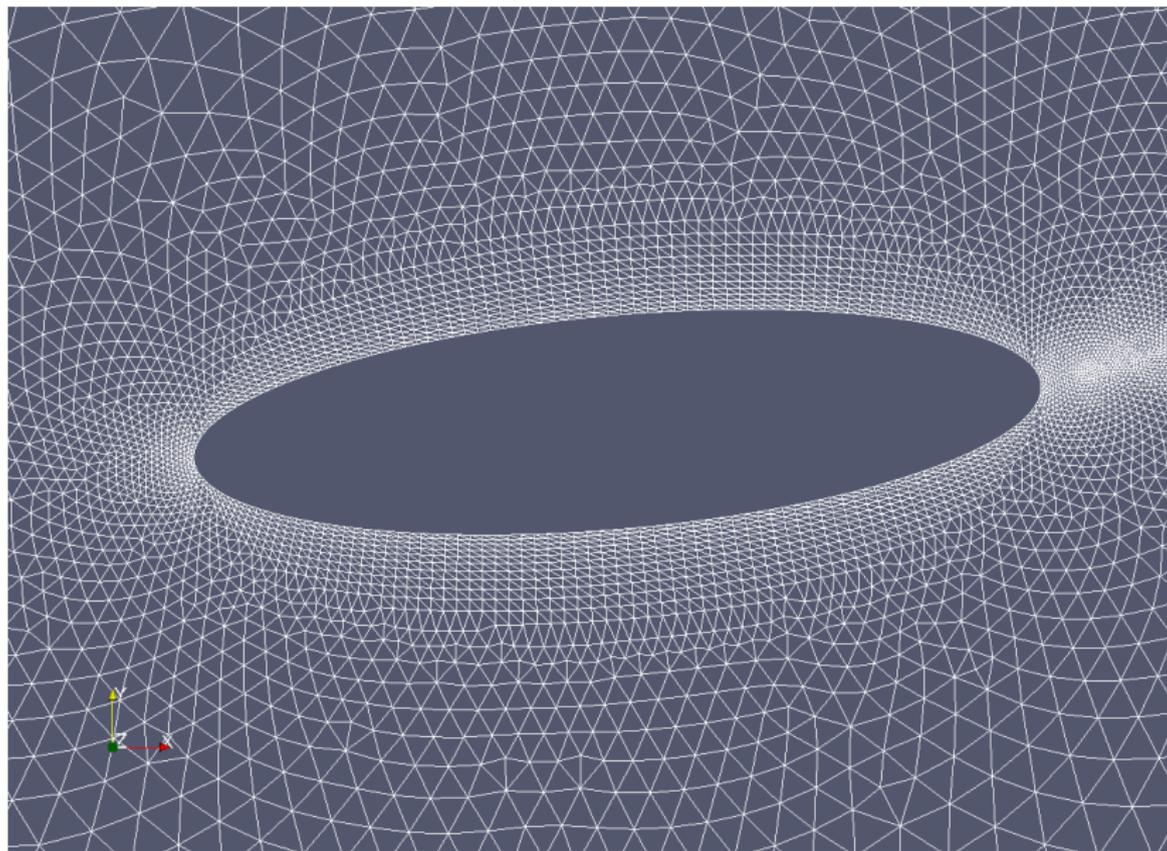
Reference grid



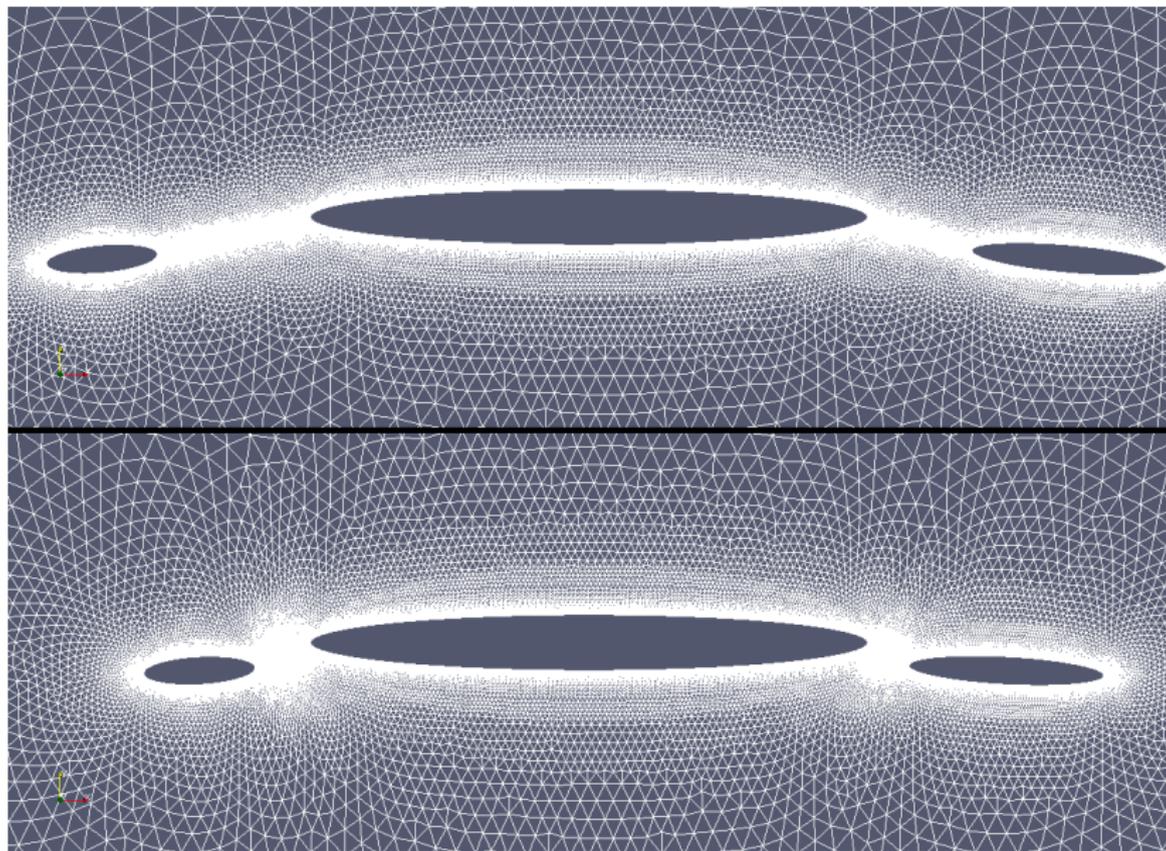
Reference grid



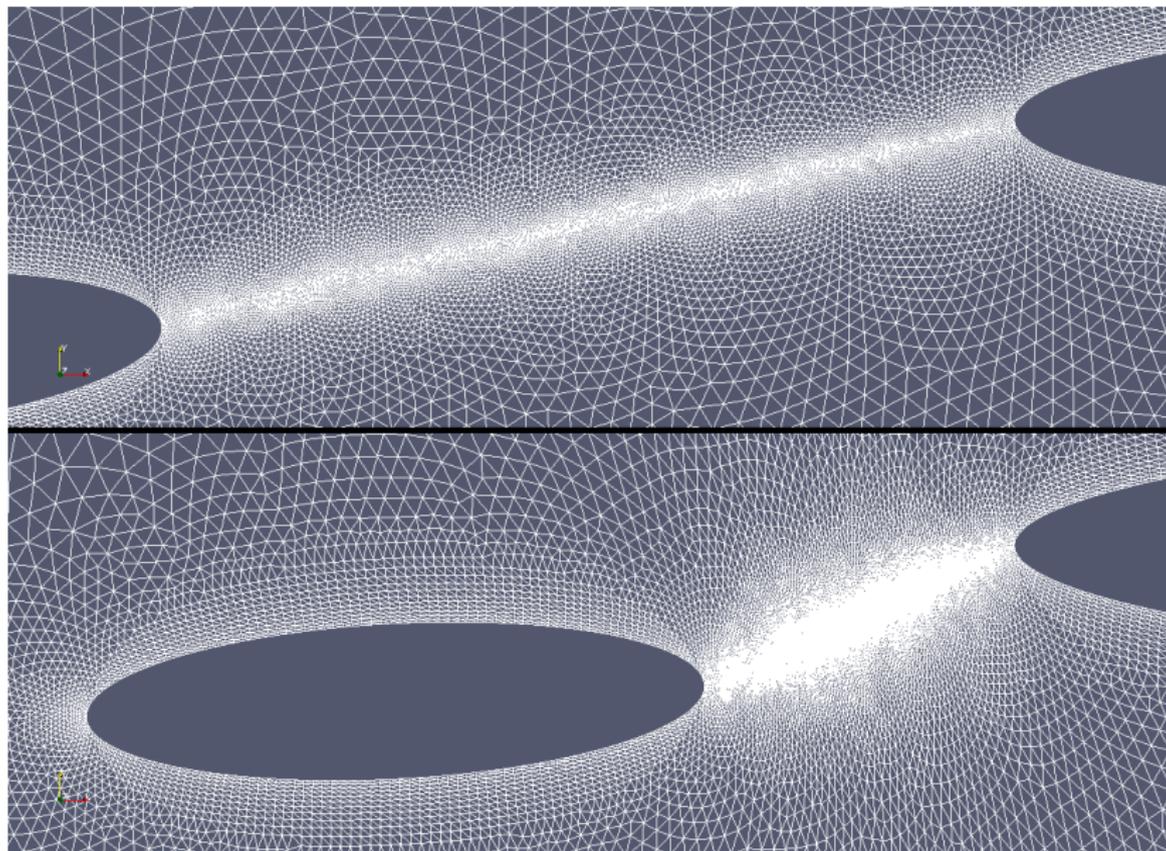
Reference grid: Around first ellipse



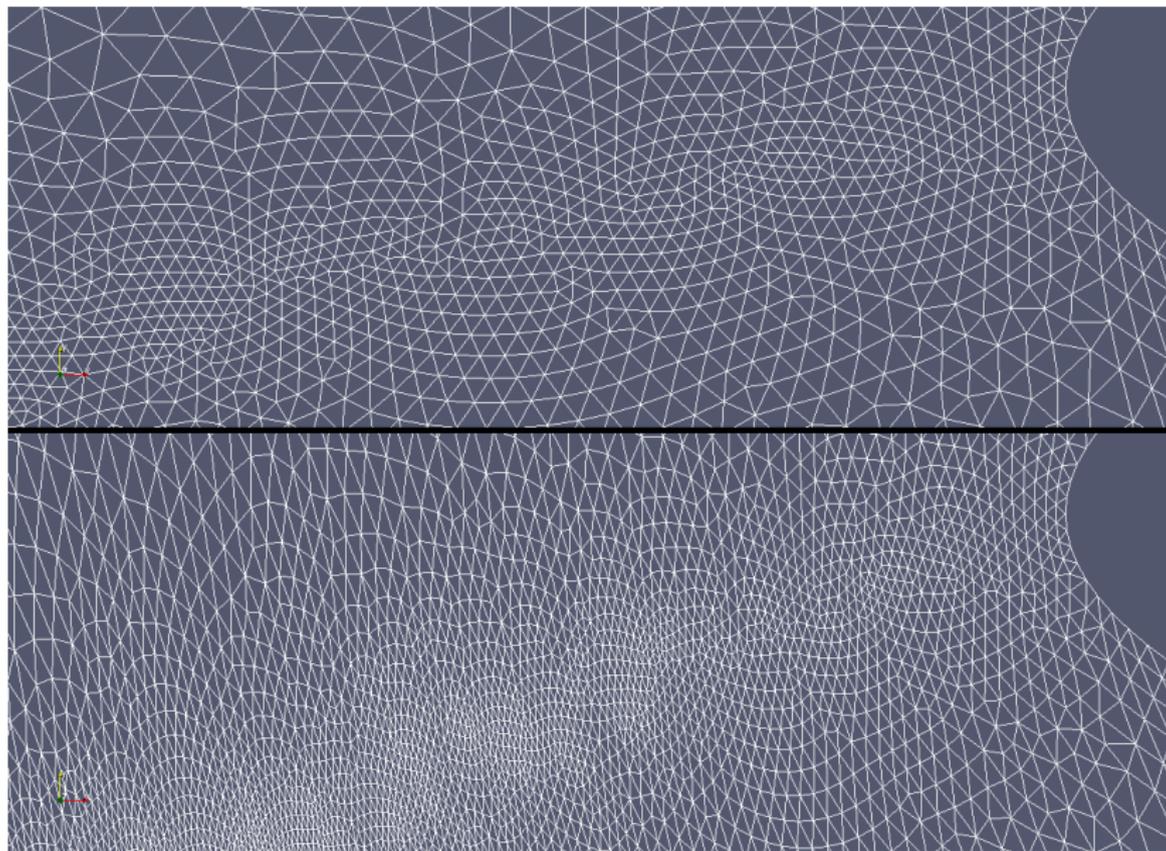
Reference and target grid



Reference and target grid: B/w first and second ellipse



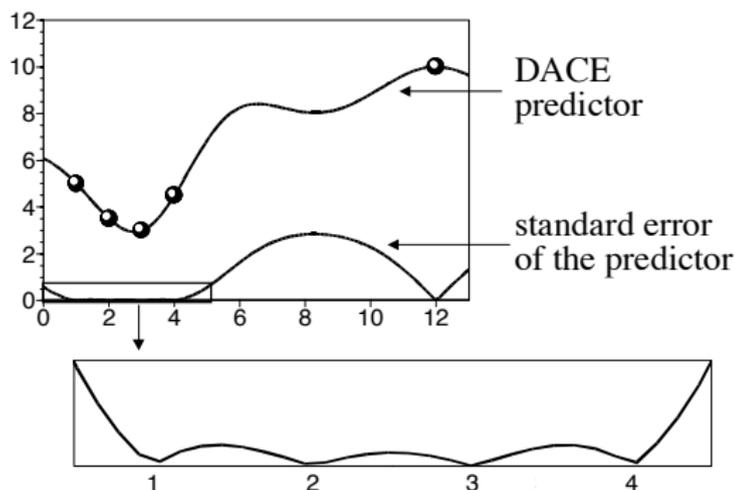
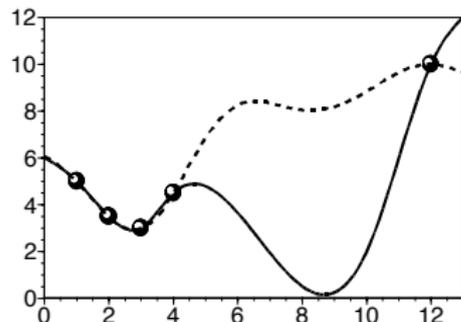
Reference and target grid: B/W first and second ellipse



- Global models: provide **global trends** in objective function
 - ▶ Faster convergence towards global optimum
- Metamodels are approximate, inaccurate
- **Not possible** to construct accurate metamodel **in one-shot**
- Difficult to construct **uniformly accurate** model in high dimensions
 - ▶ *Curse of dimensionality*
- Model must be **accurate** in **regions of optima**
- But need to sufficiently **explore** the design space
- Balance between **exploration** and **exploitation**

Gaussian process models

- Treat results of a computer code as a **stochastic** process !!!
- Provides an estimate of the **variance** in predicted value



- Statistical lower bound

$$f_M(x) = \tilde{J}(x) - \kappa \tilde{s}(x)$$

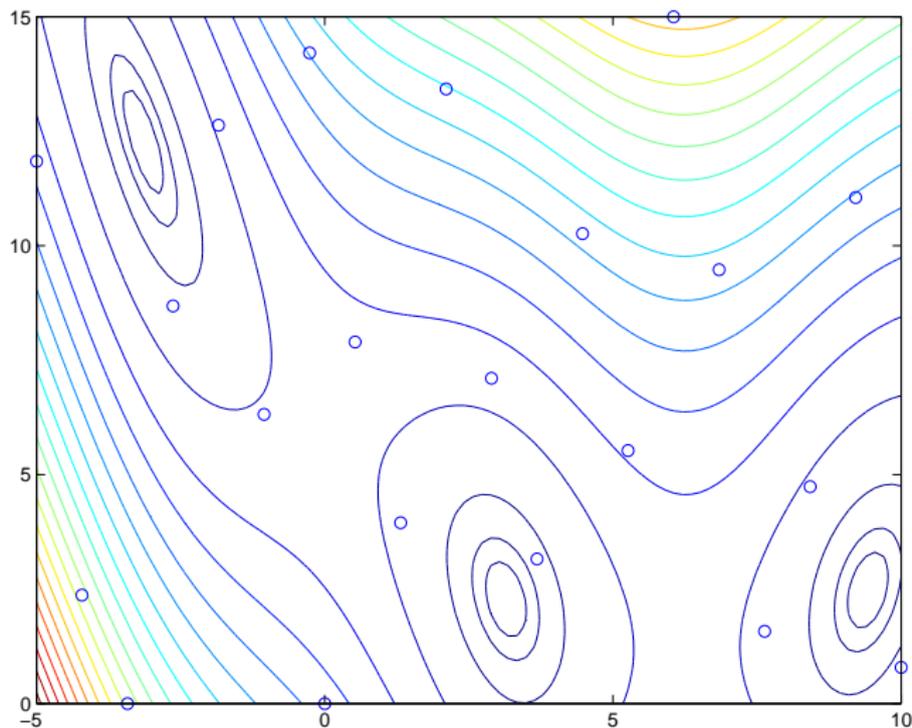
- Probability of improvement

$$\text{PoI}(x) = \Phi \left(\frac{T - \tilde{J}(x)}{\tilde{s}(x)} \right)$$

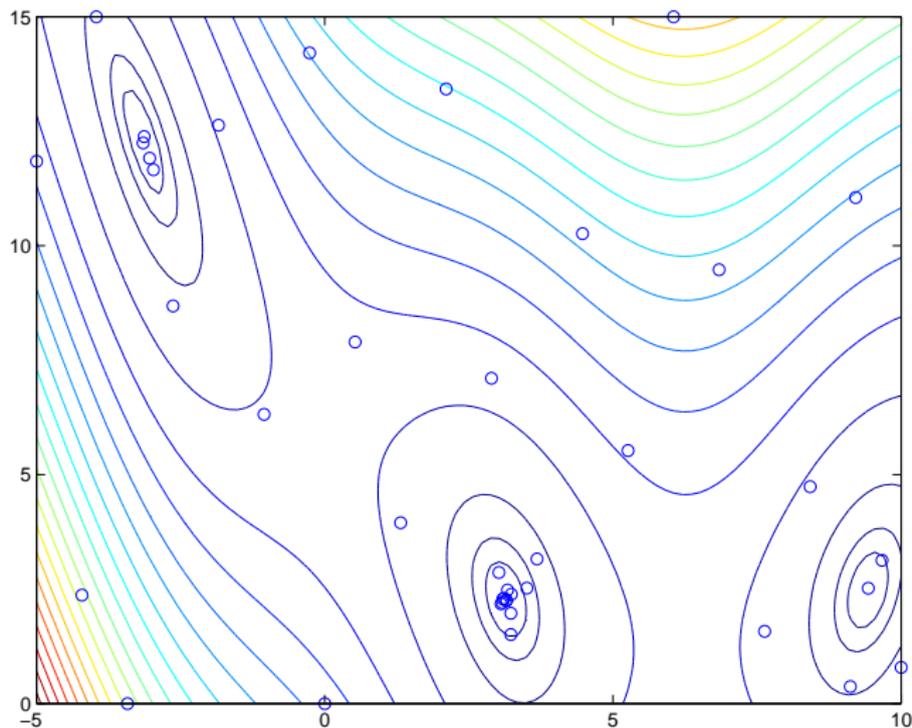
- Expected improvement

$$\text{EI}(x) = \tilde{s}(x)[u\Phi(u) + \phi(u)], \quad u(x) = \frac{J_{\min} - \tilde{J}(x)}{\tilde{s}(x)}$$

Minimization of 2-D Branin function: Initial database

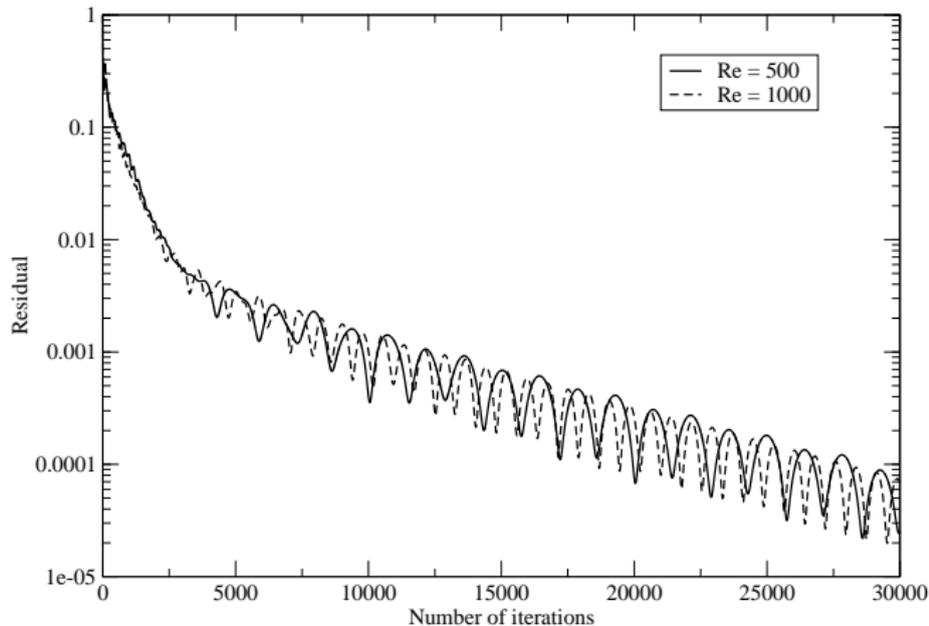


Minimization of 2-D Branin function: after 20 iter

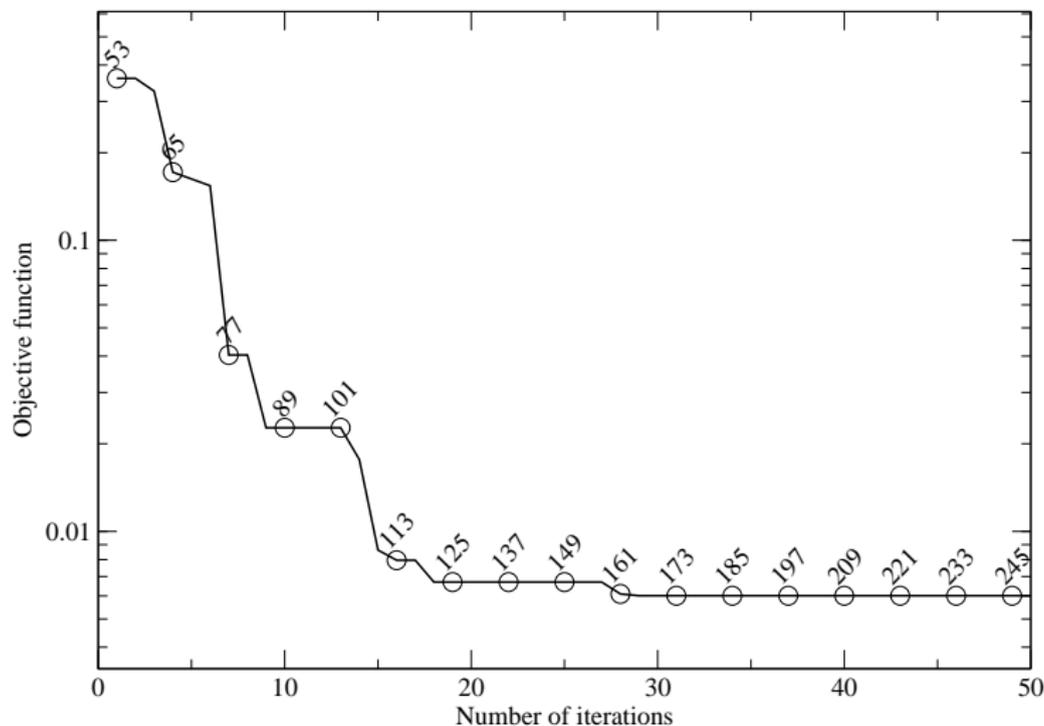


- 6 design variables
- Initial database of 48 using LHS
- 4 merit functions based on statistical lower bound with $\kappa = 0, 1, 2, 3$
- Gaussian process models
- Merit functions minimized using PSO

Convergence of CFD iterations for target configuration

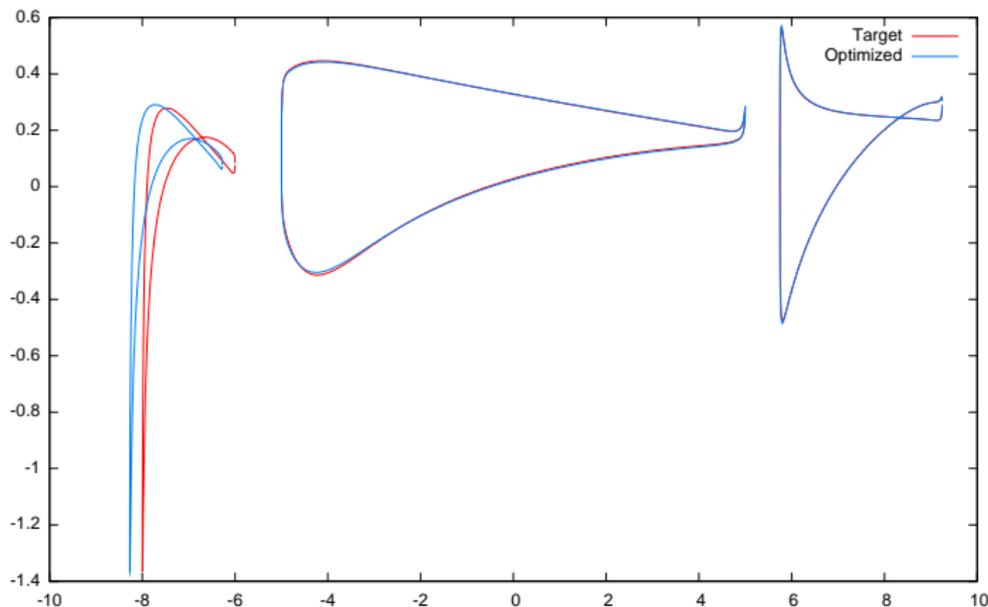


Convergence of optimization for Re=500



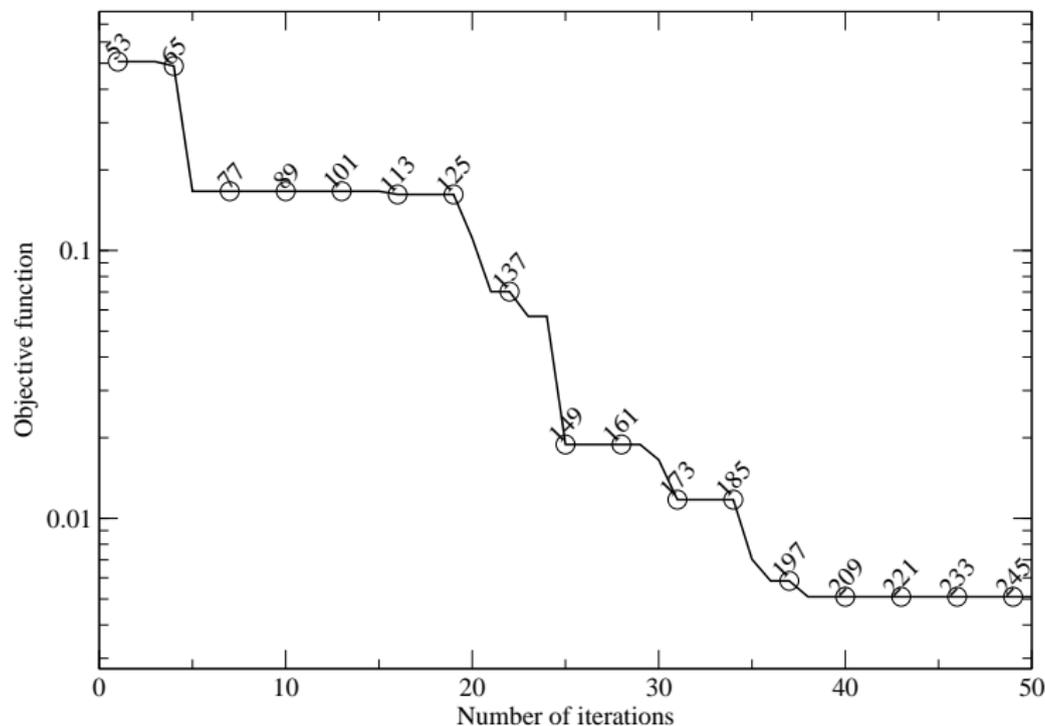
Best objective function value = 6.00×10^{-3} (normalized) or 1.25×10^{-4}

Pressure coefficient for $Re = 500$



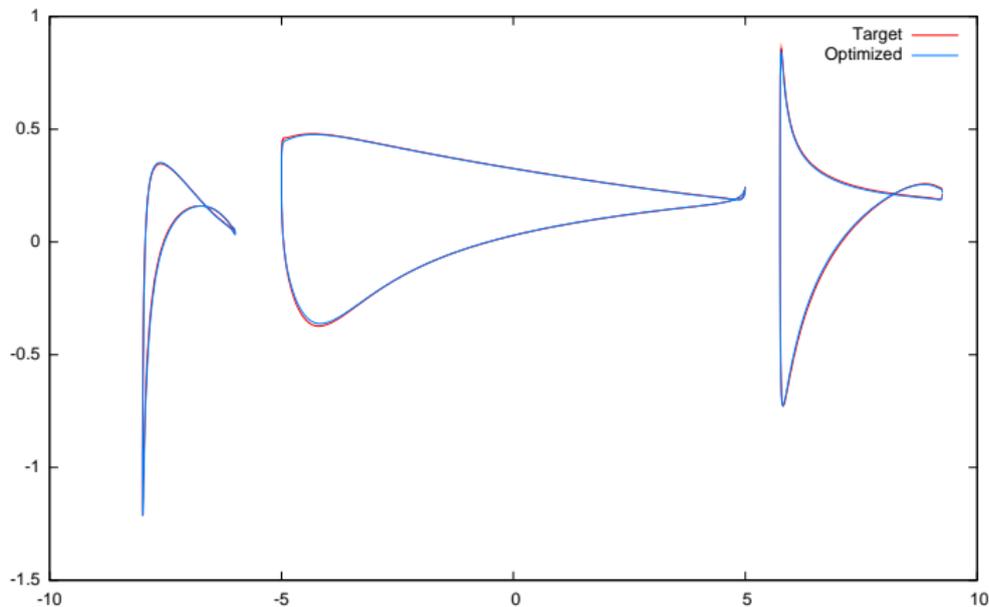
	x_1	y_1	α_1	x_3	y_3	α_3
Target	-7.5	-0.5	-3.5	7.5	-0.5	3.0
Opt	-7.271	-0.541	-3.232	7.494	-0.518	3.120

Convergence of optimization for Re=1000



Best objective function value = 5.09×10^{-3} (normalized) or 1.06×10^{-4}

Pressure coefficient for $Re = 1000$



	x_1	y_1	α_1	x_3	y_3	α_3
Target	-7.5	-0.5	-3.5	7.5	-0.5	3.0
Opt	-6.993	-0.504	-2.675	7.498	-0.497	2.641

- Grid is deformed in smooth way by RBF interpolation.
We expect objective function to depend continuously on the design variables.
- CFD has good convergence and pressure is smooth on the ellipses
- Objective is reduced by 3 orders of magnitude for both Reynolds numbers
- But for $Re=500$, position of first ellipse is not well recovered
- Objective function could be insensitive to position of first ellipse.
This behaviour has been seen by other presentations in the first workshop.
- For $Re=1000$, position is recovered well but both angles are far off from the target values.
But pressure looks quite close to target pressure.
- Global optimization methods not able to precisely locate the optimum. Performance could be improved by a trust region approach and/or using some gradient information.