# A class of singular Fourier integral operators in Synthetic Aperture Radar imaging 

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#### Abstract

In this article, we analyze the microlocal properties of the linearized forward scattering operator $F$ and the normal operator $F^{*} F$ (where $F^{*}$ is the $L^{2}$ adjoint of $F$ ) which arises in Synthetic Aperture Radar imaging for the common midpoint acquisition geometry. When $F^{*}$ is applied to the scattered data, artifacts appear. We show that $F^{*} F$ can be decomposed as a sum of four operators, each belonging to a class of distributions associated to two cleanly intersecting Lagrangians, $I^{p, l}\left(\Lambda_{0}, \Lambda_{1}\right)$, thereby explaining the latter artifacts. © 2012 Elsevier Inc. All rights reserved.


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## 1. Introduction

In this article, we analyze the microlocal properties of a transform that appears in Synthetic Aperture Radar (SAR) imaging. In SAR imaging, a region on the surface of the earth is illuminated by an electromagnetic transmitter and an image of the region is reconstructed based on the measurement of scattered waves at a receiver. For in-depth treatments of SAR imaging, we refer the reader to $[1,2]$. The transform we study appears as a result of a common midpoint acquisition geometry: the transmitter and receiver move at equal speeds away from a common midpoint along a straight line. This geometry is of interest in bistatic imaging and in certain multiple scattering scenarios [21]. We first consider the linearized scattering operator $F$ and show that it is a Fourier integral operator (FIO). Since the conventional method of reconstructing the image of an object involves "backprojecting" the scattered data, we next study the composition of $F$ with its $L^{2}$ adjoint $F^{*}$. One of the main goals of this article is to understand the distribution class of the kernel of $F^{*} F$.

In general the composition of two FIOs is not an FIO. One needs additional geometric conditions such as the transverse intersection condition [16] or the clean intersection condition [4] to make the composition operator again an FIO. When these assumptions fail to be satisfied, it is very useful to study the canonical relation associated to an FIO by considering the left and the right projections. More precisely, let $X$ and $Y$ be manifolds and let $I^{m}(X, Y ; C)$ be the class of FIOs $F: \mathcal{E}^{\prime}(X) \rightarrow \mathcal{D}^{\prime}(Y)$ of order $m$ associated to the canonical relation $C \subset\left(T^{*} Y \times T^{*} X\right) \backslash\{0\}$ and denote by $\pi_{L}: C \rightarrow T^{*} Y, \pi_{R}: C \rightarrow T^{*} X$, the left and right projections respectively. Where and how these projections drop rank determine the nature of the normal operator $F^{*} F$.

Several authors have analyzed the nature of the canonical relation and the singularities of the left and right projections in many contexts including scattering theory, integral geometry and harmonic analysis $[18,14,11,13,12,9,10,20,5-8,17]$. The singularities which appear in previous work related to SAR $[20,5,6,17]$ are folds and blowdowns, that is, $\pi_{L}$ and $\pi_{R}$ have both fold singularities or $\pi_{L}$ has a fold singularity and $\pi_{R}$ has a blowdown singularity. These singularities will be defined in Section 3. Then it is known that the corresponding normal operator belongs to a class of distributions $I^{2 m, 0}(\Delta, \widetilde{C})$ introduced in [15] (and defined in Section 3). This means that the adjoint operator $F^{*}$ introduces an additional singularity given by $\widetilde{C}$ apart from the initial one given by $\Delta$. For example, in the case of straight line acquisition geometry in monostatic radar - the transmitter and receiver are located at the same point and move along a straight line - the additional Lagrangian $\widetilde{C}$ is reflected in the fact that there is a natural left-right ambiguity in SAR; reflectors on one side of the flight path can give the same signal as reflectors on the other side. This implies that one can only recover the singularities of the even part of the target function. In other words, there is cancellation of certain singularities. Stefanov and Uhlmann prove that such cancellation of singularities can occur even with curved flight paths [22].

In this article, the linearized scattering operator $F$ exhibits a new feature: both projections drop rank by one on a disjoint union of two smooth hypersurfaces $\Sigma_{1} \cup \Sigma_{2}$. On each of them, $\pi_{L}$ is a projection with fold singularities and $\pi_{R}$ is a projection with blowdown singularities. Note that this is different from the situation in [11] where they study a class of geodesic X-ray transforms on manifolds in which the singularities of the left and right projections are in the reverse order. We then show that $F^{*} F$ belongs to the class $I^{2 m, 0}\left(\Delta, C_{1}\right)+I^{2 m, 0}\left(\Delta, C_{2}\right)+$ $I^{2 m, 0}\left(C_{1}, C_{3}\right)+I^{2 m, 0}\left(C_{2}, C_{3}\right)$ (where these classes are given in Definition 3.6). This means that the adjoint operator $F^{*}$ adds three more singularities given by $C_{1}, C_{2}, C_{3}$ in addition to the true reconstructed singularity given by $\Delta$. We clarify this in detail in Section 5. The main tool for
proving our result is the iterated regularity property; a characteristic property of $I^{p, l}$ classes [13, Proposition 1.35].

## 2. Statement of the main results

### 2.1. The linearized scattering model

For simplicity, we assume that both the transmitter and receiver are at the same height $h>0$ above the ground, $x_{3}=0$, at all times and move in opposite directions at equal speeds along the line parallel the $x_{1}$ axis and containing the common midpoint $(0,0, h)$. Such a model arises when considering signals which have scattered from a wall within the vicinity of a scatterer and can be understood in the context of the method of images; see [21] for more details.

Let $\gamma_{T}(s)=(s, 0, h)$ and $\gamma_{R}(s)=(-s, 0, h)$ for $s \in(0, \infty)$ be the trajectories of the transmitter and receiver respectively.

The linearized model for the scattered signal we will use in this article is from [21]

$$
\begin{equation*}
d(s, t):=F V(s, t)=\int e^{-\mathrm{i} \omega\left(t-\frac{1}{c_{0}} R(s, x)\right)} a(s, x, \omega) V(x) \mathrm{d} x \mathrm{~d} \omega \tag{1}
\end{equation*}
$$

for $(s, t) \in Y=(0, \infty) \times(0, \infty)$, where $V(x)=V\left(x_{1}, x_{2}\right)$ is the function modeling the object on the ground, $R(s, x)$ is the bistatic distance:

$$
R(s, x)=\left|\gamma_{T}(s)-x\right|+\left|x-\gamma_{R}(s)\right|,
$$

$c_{0}$ is the speed of electromagnetic wave in free-space and the amplitude term $a$ is given by

$$
\begin{equation*}
a(s, x, \omega)=\frac{\omega^{2} p(\omega)}{16 \pi^{2}\left|\gamma_{T}(s)-x\right|\left|\gamma_{R}(s)-x\right|} \tag{2}
\end{equation*}
$$

where $p$ is the Fourier transform of the transmitted waveform.

### 2.2. Preliminary modifications on the scattered data

For simplicity, from now on we will assume that $c_{0}=1$. To make the composition of $F$ with its $L^{2}$ adjoint $F^{*}$ to be well-defined, we multiply $d(s, t)$ by an infinitely differentiable function $f(s, t)$ identically equal to 1 in a compact subset of $(0, \infty) \times(0, \infty)$ and supported in a slightly bigger compact subset of $(0, \infty) \times(0, \infty)$. We rename $f \cdot d$ as $d$ again.

As we will see below, our method cannot image a neighborhood of the common midpoint. That is, if the transmitter and receiver are at $(s, 0, h)$ and $(-s, 0, h)$ respectively, we cannot image a neighborhood of the origin on the horizontal plane of the earth, $x_{3}=0$. Therefore we modify $d$ further by considering a smooth function $g(s, t)$ such that

$$
\begin{equation*}
g(s, t)=0 \quad \text { for }(s, t):\left|t-2 \sqrt{s^{2}+h^{2}}\right|<20 \epsilon^{2} / h \tag{3}
\end{equation*}
$$

where $\epsilon>0$ is given. Again we let $g \cdot d$ to be $d$ and $g \cdot a$ to be $a$. The choice of constant on the right-hand side of (3) will be justified in Appendix B. Our forward operator is

$$
\begin{equation*}
d(s, t)=\int e^{-\mathrm{i} \varphi(s, t, x, \omega)} a(s, t, x, \omega) V(x) \mathrm{d} x \mathrm{~d} \omega \tag{4}
\end{equation*}
$$

where

$$
\begin{equation*}
\varphi(s, t, x, \omega)=\omega\left(t-\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}-\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}\right) \tag{5}
\end{equation*}
$$

From now on, we will denote the ground (the plane $x_{3}=0$ ) by $X$, thus the points on $X$ will be denoted $x=\left(x_{1}, x_{2}\right)$.

We assume that the amplitude function $a \in S^{m+\frac{1}{2}}$, that is, it satisfies the following estimate: For every compact set $K \subset Y \times X$, non-negative integer $\alpha$, and 2-indexes $\beta=\left(\beta_{1}, \beta_{2}\right)$ and $\gamma$, there is a constant $c$ such that

$$
\begin{equation*}
\left|\partial_{\omega}^{\alpha} \partial_{s}^{\beta_{1}} \partial_{t}^{\beta_{2}} \partial_{x}^{\gamma} a(s, t, x, \omega)\right| \leqslant c(1+|\omega|)^{m+(1 / 2)-\alpha} \tag{6}
\end{equation*}
$$

This assumption is satisfied if the transmitted waveform from the antenna is approximately a Dirac delta distribution.

With these modifications, we show that $F$ is a Fourier integral operator of order $m$ and study the properties of the natural projection maps from the canonical relation of $F$. Our first main result is the following:

Theorem 2.1. Let $F$ be as in (4). Then:
(a) $F$ is an $F I O$ of order $m$.
(b) The canonical relation $C$ associated to $F$ is given by

$$
\begin{align*}
C= & \left\{\left(s, t,-\omega\left(\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}-\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right),-\omega\right.\right. \\
& x_{1}, x_{2},-\omega\left(\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}+\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right) \\
& \left.-\omega\left(\frac{x_{2}}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}+\frac{x_{2}}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right)\right) \\
& s>0, t=\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}+\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}} \\
& x \neq 0, \text { and } \omega \neq 0\} \tag{7}
\end{align*}
$$

and $C$ has global parameterization

$$
(0, \infty) \times\left(\mathbb{R}^{2} \backslash 0\right) \times(\mathbb{R} \backslash 0) \ni\left(s, x_{1}, x_{2}, \omega\right) \mapsto C
$$

(c) Let $\pi_{L}: C \rightarrow T^{*} Y$ and $\pi_{R}: C \rightarrow T^{*} X$ be the left and right projections respectively. Then $\pi_{L}$ and $\pi_{R}$ drop rank simply by one on a set $\Sigma=\Sigma_{1} \cup \Sigma_{2}$ where in the coordinates $(s, x, \omega)$,
$\Sigma_{1}=\left\{\left(s, x_{1}, 0, \omega\right)\left|s>0,\left|x_{1}\right|>\epsilon^{\prime}, \omega \neq 0\right\}\right.$ and $\Sigma_{2}=\left\{\left(s, 0, x_{2}, \omega\right)\left|s>0,\left|x_{2}\right|>\epsilon^{\prime}\right.\right.$, $\omega \neq 0\}$ for $0<\epsilon^{\prime}$ small enough.
(d) $\pi_{L}$ has a fold singularity along $\Sigma$.
(e) $\pi_{R}$ has a blowdown singularity along $\Sigma$.

Remark 2.2. Note that due to the function $g(s, t)$ of (3) in the amplitude, it is enough to consider only points in $C$ that are strictly away from $\{(s, 0, \omega): s>0, \omega \neq 0\}$. This is reflected in the definitions of $\Sigma_{1}$ and $\Sigma_{2}$, where $\left|x_{1}\right|$ and $\left|x_{2}\right|$, respectively, are strictly positive.

Remark 2.3. Note that $C$ is even with respect to both $x_{1}$ and $x_{2}$. In other words $C$ is a four-to-one relation. This observation suggests that $\pi_{L}$ (respectively $\pi_{R}$ ) has two fold (respectively blowdown) sets. See Proposition 4.3.

We then analyze the normal operator $F^{*} F$. Our next main result is the following:

Theorem 2.4. Let $F$ be as in (4) of order $m$. Then $F^{*} F$ can be decomposed into a sum belonging to $I^{2 m, 0}\left(\Delta, C_{1}\right)+I^{2 m, 0}\left(\Delta, C_{2}\right)+I^{2 m, 0}\left(C_{1}, C_{3}\right)+I^{2 m, 0}\left(C_{2}, C_{3}\right)$ where these classes are given in Definition 3.6.

In Remark 5.7, we will explain why the added singularities given by $C_{1}, C_{2}, C_{3}$ have the same strength as the object singularities given by $\Delta$.

## 3. Preliminaries

### 3.1. Singularities and $I^{p, l}$ classes

In this section we will define fold and blowdown singularities and describe the $I^{p, l}$ class of distributions required for the analysis of the composition operator $F^{*} F$.

Definition 3.1. (See [14, pp. 109-111].) Let $M$ and $N$ be manifolds of dimension $n$ and let $f: M \rightarrow N$ be $C^{\infty}$. Let $\Omega$ be a non-vanishing volume form on $N$ and define $\Sigma=$ $\left\{\sigma \in M: f^{*} \Omega(\sigma)=0\right\}$, that is, $\Sigma$ is the set of critical points of $f$. Note that, equivalently, $\Sigma$ is defined by the vanishing of the determinant of the Jacobian of $f$.
(a) If for all $\sigma \in \Sigma$, we have (i) the corank of $f$ at $\sigma$ is 1 , (ii) $\operatorname{ker}\left(\mathrm{d} f_{\sigma}\right) \cap T_{\sigma} \Sigma=\{0\}$, (iii) $f^{*} \Omega$ vanishes exactly to first order on $\Sigma$, then we say that $f$ is a fold.
(b) If for all $\sigma \in \Sigma$, we have (i) the rank of $f$ is constant; let us call this constant $k$, (ii) $\operatorname{ker}\left(\mathrm{d} f_{\sigma}\right) \subset T_{\sigma} \Sigma$, (iii) $f^{*} \Omega$ vanishes exactly to order $n-k$ on $\Sigma$, then we say that $f$ is a blowdown.

We now define $I^{p, l}$ classes. They were first introduced by Melrose and Uhlmann [19], Guillemin and Uhlmann [15] and Greenleaf and Uhlmann [13] and they were used in the context of radar imaging in [20,5,6].

Definition 3.2. Two submanifolds $M$ and $N$ intersect cleanly if $M \cap N$ is a smooth submanifold and $T(M \cap N)=T M \cap T N$.

Let us consider the following example:
Example 3.3. Let $\tilde{\Lambda}_{0}=\Delta_{T * \mathbb{R}^{n}}=\left\{(x, \xi ; x, \xi) \mid x \in \mathbb{R}^{n}, \xi \in \mathbb{R}^{n} \backslash 0\right\}$ be the diagonal in $T^{*} \mathbb{R}^{n} \times$ $T^{*} \mathbb{R}^{n}$ and let $\widetilde{\Lambda}_{1}=\left\{\left(x^{\prime}, x_{n}, \xi^{\prime}, 0 ; x^{\prime}, y_{n}, \xi^{\prime}, 0\right) \mid x^{\prime} \in \mathbb{R}^{n-1}, \xi^{\prime} \in \mathbb{R}^{n-1} \backslash 0\right\}$. Then, $\widetilde{\Lambda}_{0}$ intersects $\widetilde{\Lambda}_{1}$ cleanly in codimension 1 .

Now we define the class of product-type symbols $S^{p, l}(m, n, k)$.
Definition 3.4. $S^{p, l}(m, n, k)$ is the set of all functions $a(z, \xi, \sigma) \in C^{\infty}\left(\mathbb{R}^{m} \times \mathbb{R}^{n} \times \mathbb{R}^{k}\right)$ such that for every $K \subset \mathbb{R}^{m}$ and every $\alpha \in \mathbb{Z}_{+}^{m}, \beta \in \mathbb{Z}_{+}^{n}, \gamma \in \mathbb{Z}_{+}^{k}$ there is $c_{K, \alpha, \beta, \gamma}$ such that

$$
\left|\partial_{z}^{\alpha} \partial_{\xi}^{\beta} \partial_{\sigma}^{\gamma} a(z, \xi, \sigma)\right| \leqslant c_{K, \alpha, \beta, \gamma}(1+|\xi|)^{p-|\beta|}(1+|\sigma|)^{l-|\gamma|}, \quad \forall(z, \xi, \tau) \in K \times \mathbb{R}^{n} \times \mathbb{R}^{k}
$$

Since any two sets of cleanly intersecting Lagrangians are equivalent [15], we first define $I^{p, l}$ classes for the case in Example 3.3.

Definition 3.5. (See [15].) Let $I^{p, l}\left(\tilde{\Lambda}_{0}, \tilde{\Lambda}_{1}\right)$ be the set of all distributions $u$ such that $u=u_{1}+u_{2}$ with $u_{1} \in C_{0}^{\infty}$ and

$$
u_{2}(x, y)=\int e^{i\left(\left(x^{\prime}-y^{\prime}\right) \cdot \xi^{\prime}+\left(x_{n}-y_{n}-s\right) \cdot \xi_{n}+s \cdot \sigma\right)} a(x, y, s ; \xi, \sigma) \mathrm{d} \xi \mathrm{~d} \sigma \mathrm{~d} s
$$

with $a \in S^{p^{\prime}, l^{\prime}}$ where $p^{\prime}=p-\frac{n}{2}+\frac{1}{2}$ and $l^{\prime}=l-\frac{1}{2}$.
Let $\left(\Lambda_{0}, \Lambda_{1}\right)$ be a pair of cleanly intersection Lagrangians in codimension 1 and let $\chi$ be a canonical transformation which maps $\left(\Lambda_{0}, \Lambda_{1}\right)$ into $\left(\tilde{\Lambda}_{0}, \widetilde{\Lambda}_{1}\right)$ and maps $\Lambda_{0} \cap \Lambda_{1}$ to $\widetilde{\Lambda}_{0} \cap \widetilde{\Lambda}_{1}$, where $\widetilde{\Lambda}_{j}$ are from Example 3.3. Next we define the $I^{p, l}\left(\Lambda_{0}, \Lambda_{1}\right)$.

Definition 3.6. (See [15].) Let $I^{p, l}\left(\Lambda_{0}, \Lambda_{1}\right)$ be the set of all distributions $u$ such that $u=u_{1}+$ $u_{2}+\sum v_{i}$ where $u_{1} \in I^{p+l}\left(\Lambda_{0} \backslash \Lambda_{1}\right), u_{2} \in I^{p}\left(\Lambda_{1} \backslash \Lambda_{0}\right)$, the sum $\sum v_{i}$ is locally finite and $v_{i}=A w_{i}$ where $A$ is a zero order FIO associated to $\chi^{-1}$, the canonical transformation from above, and $w_{i} \in I^{p, l}\left(\tilde{\Lambda}_{0}, \widetilde{\Lambda}_{1}\right)$.

If $u$ is the Schwartz kernel of the linear operator $F$, then we say $F \in I^{p, l}\left(\Lambda_{0}, \Lambda_{1}\right)$.
This class of distributions is invariant under FIOs associated to canonical transformations which map the pair $\left(\Lambda_{0}, \Lambda_{1}\right)$ to itself and the intersection $\Lambda_{0} \cap \Lambda_{1}$ to itself. If $F \in I^{p, l}\left(\Lambda_{0}, \Lambda_{1}\right)$ then $F \in I^{p+l}\left(\Lambda_{0} \backslash \Lambda_{1}\right)$ and $F \in I^{p}\left(\Lambda_{1} \backslash \Lambda_{0}\right)$ [15]. Here by $F \in I^{p+l}\left(\Lambda_{0} \backslash \Lambda_{1}\right)$, we mean that the Schwartz kernel of $F$ belongs to $I^{p+l}\left(\Lambda_{0} \backslash \Lambda_{1}\right)$ microlocally away from $\Lambda_{1}$.

One way to show that a distribution belongs to $I^{p, l}$ class is by using the iterated regularity property:

Proposition 3.7. (See [13, Proposition 1.35].) If $u \in \mathcal{D}^{\prime}(X \times Y)$ then $u \in I^{p, l}\left(\Lambda_{0}, \Lambda_{1}\right)$ if there is an $s_{0} \in R$ such that for all first order pseudodifferential operators $P_{i}$ with principal symbols vanishing on $\Lambda_{0} \cup \Lambda_{1}$, we have $P_{1} P_{2} \ldots P_{r} u \in H_{\mathrm{loc}}^{s_{0}}$.

## 4. Analysis of the operator $F$

In this section, we prove Theorem 2.1, as a result of Lemma 4.1 and Proposition 4.3.
Lemma 4.1. $F$ is an FIO of order $m$ with the canonical relation $C$ given by

$$
\begin{align*}
C= & \left\{\left(s, t,-\omega\left(\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}-\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right),-\omega\right.\right. \\
& x_{1}, x_{2},-\omega\left(\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}+\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right) \\
& \left.-\omega\left(\frac{x_{2}}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}+\frac{x_{2}}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right)\right): \\
& s>0, t=\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}+\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}} \\
& \left.x \in \mathbb{R}^{2} \backslash\{0\}, \omega \neq 0\right\} . \tag{8}
\end{align*}
$$

We note that $(0, \infty) \times\left(\mathbb{R}^{2} \backslash 0\right) \times(\mathbb{R} \backslash 0) \ni\left(s, x_{1}, x_{2}, \omega\right) \mapsto C$ is a global parametrization of $C$.
We will use the coordinates $(s, x, \omega)$ in this lemma from now on to describe $C$ and subsets of $C$.

Proof of Lemma 4.1. The phase function $\varphi$ is non-degenerate with $\partial_{x} \varphi, \partial_{s, t} \varphi$ nowhere 0 whenever $\partial_{\omega} \varphi=0$. We should mention that $\nabla \partial_{\omega} \varphi \neq 0$. (Note that in order for $\partial_{x} \varphi$ to be nowhere 0 , we require exclusion of the common midpoint from our analysis.) This observation is needed to show $F$ is an FIO rather than just a Fourier integral distribution. Recalling that $a$ satisfies amplitude estimates (6), we conclude that $F$ is an FIO [23]. Also since $a$ is of order $m+\frac{1}{2}$, the order of the FIO is $m$ [3, Definition 3.2.2]. By definition [16, Eq. (3.1.2)]

$$
C=\left\{\left(\left(s, t, \partial_{s} \varphi, \partial_{t} \varphi\right) ;\left(x,-\partial_{x} \varphi\right)\right): \partial_{\omega} \varphi=0\right\} .
$$

A calculation using this definition establishes (8). Furthermore, it is easy to see that ( $s, x_{1}, x_{2}, \omega$ ) is a global parametrization of $\Lambda$.

Remark 4.2. In the SAR application, $a$ has order 2 which makes operator $F$ of order $\frac{3}{2}$. But from now on will consider that $F$ has order $m$.

Proposition 4.3. Denoting the restriction of the left and right projections to $C$ by $\pi_{L}$ and $\pi_{R}$ respectively, we have:
(a) $\pi_{L}$ and $\pi_{R}$ drop rank by one on a set $\Sigma=\Sigma_{1} \cup \Sigma_{2}$.

Here we use the global coordinates from Lemma 4.1.
(b) $\pi_{L}$ has a fold singularity along $\Sigma$.
(c) $\pi_{R}$ has a blowdown singularity along $\Sigma$.

Proof. Let $A=\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}$ and $B=\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}$. We have

$$
\pi_{L}\left(x_{1}, x_{2}, s, \omega\right)=\left(s, A+B,-\left(\frac{x_{1}-s}{A}-\frac{x_{1}+s}{B}\right) \omega,-\omega\right)
$$

and

$$
\mathrm{d} \pi_{L}=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
\frac{x_{1}-s}{A}+\frac{x_{1}+s}{B} & \frac{x_{2}}{A}+\frac{x_{2}}{B} & * & 0 \\
-\omega\left(\frac{x_{2}^{2}+h^{2}}{A^{3}}-\frac{x_{2}^{2}+h^{2}}{B^{3}}\right) & \omega\left(\frac{\left(x_{1}-s\right) x_{2}}{A^{3}}-\frac{\left(x_{1}+s\right) x_{2}}{B^{3}}\right) & * & * \\
0 & 0 & 0 & -1
\end{array}\right)
$$

where $*$ denotes derivatives that are not needed for the calculation. The determinant is

$$
\begin{equation*}
\operatorname{det} \mathrm{d} \pi_{L}=\frac{4 x_{1} x_{2} s \omega}{A^{2} B^{2}}\left(1+\frac{x_{1}^{2}-s^{2}+x_{2}^{2}+h^{2}}{A B}\right) \tag{9}
\end{equation*}
$$

We have that $s>0$ and the number in the parenthesis is a positive number by Lemma 4.4 below.

Therefore, $\pi_{L}$ drops rank by one on $\Sigma=\Sigma_{1} \cup \Sigma_{2}$. To show $\mathrm{d}\left(\operatorname{det}\left(\mathrm{d} \pi_{L}\right)\right)$ is nowhere zero on $\Sigma$, one uses the product rule in (9) and the fact that the differential of $\frac{4 x_{1} x_{2} s \omega}{A^{2} B^{2}}$ is never zero on $\Sigma$ and the inequality in Lemma 4.4.

On $\Sigma_{1}$ the kernel of d $\pi_{L}$ is $\frac{\partial}{\partial x_{2}}$ which is transversal to $\Sigma_{1}$ and on $\Sigma_{2}$ the kernel of d $\pi_{L}$ is $\frac{\partial}{\partial x_{1}}$ which is transversal to $\Sigma_{2}$. This means that $\pi_{L}$ has a fold singularity along $\Sigma$.

Similarly,

$$
\pi_{R}\left(x_{1}, x_{2}, s, \omega\right)=\left(x_{1}, x_{2},-\left(\frac{x_{1}-s}{A}+\frac{x_{1}+s}{B}\right) \omega,-\left(\frac{x_{2}}{A}+\frac{x_{2}}{B}\right) \omega\right)
$$

Then

$$
\mathrm{d} \pi_{R}=\left(\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
* & * & \omega\left(\frac{x_{2}^{2}+h^{2}}{A^{3}}-\frac{x_{2}^{2}+h^{2}}{B^{3}}\right) & -\left(\frac{x_{1}-s}{A}+\frac{x_{1}+s}{B}\right) \\
* & * & -\omega\left(\frac{\left(\frac{\left.x_{1}-s\right) x_{2}}{A^{3}}-\frac{\left(x_{1}+s\right) x_{2}}{B^{3}}\right)}{}\right. & -\left(\frac{x_{2}}{A}+\frac{x_{2}}{B}\right)
\end{array}\right)
$$

has the same determinant so $\pi_{R}$ drops rank by one on $\Sigma$ and the kernel of d $\pi_{R}$ is a linear combination of $\frac{\partial}{\partial \omega}$ and $\frac{\partial}{\partial s}$ which are tangent to both $\Sigma_{1}$ and $\Sigma_{2}$. This means that $\pi_{R}$ has a blowdown singularity along $\Sigma$.

Lemma 4.4. For all $s \neq 0$,

$$
1+\frac{x_{1}^{2}-s^{2}+x_{2}^{2}+h^{2}}{\left|x-\gamma_{T}(s)\right|\left|x-\gamma_{R}(s)\right|}>0 .
$$

Proof. Equivalently, we show that $\left(\left|x-\gamma_{T}(s) \| x-\gamma_{R}(s)\right|\right)^{2}>\left(x_{1}^{2}+x_{2}^{2}+h^{2}-s^{2}\right)^{2}$. Expanding out both sides and simplifying, we obtain $4 s^{2}\left(x_{2}^{2}+h^{2}\right)>0$ which holds for $s \neq 0$, since $h>0$. Therefore the lemma is proved.

## 5. Analysis of the normal operator $F^{*} F$

We have

$$
\begin{aligned}
F^{*} F V(x)= & \int e^{\mathrm{i} \omega\left(t-\left(\left|x-\gamma_{T}(s)\right|+\left|x-\gamma_{R}(s)\right|\right)\right)-\tilde{\omega}\left(t-\left(\left|y-\gamma_{T}(s)\right|+\left|y-\gamma_{R}(s)\right|\right)\right)} \\
& \times \overline{a(s, t, x, \omega)} a(s, t, y, \tilde{\omega}) V(y) \mathrm{d} s \mathrm{~d} t \mathrm{~d} \omega \mathrm{~d} \tilde{\omega} \mathrm{~d} y
\end{aligned}
$$

After an application of the method of stationary phase in $t$ and $\tilde{\omega}$, the Schwartz kernel of this operator is

$$
\begin{equation*}
K(x, y)=\int e^{\mathrm{i} \omega\left(\left|y-\gamma_{T}(s)\right|+\left|y-\gamma_{R}(s)\right|-\left(\left|x-\gamma_{T}(s)\right|+\left|x-\gamma_{R}(s)\right|\right)\right)} \tilde{a}(x, y, s, \omega) \mathrm{d} s \mathrm{~d} \omega \tag{10}
\end{equation*}
$$

Note that $\tilde{a} \in S^{2 m+1}$ since we assume $a \in S^{m+1 / 2}$.
Let the phase function of the kernel $K$ be denoted by

$$
\begin{equation*}
\Phi=\omega\left(\left|y-\gamma_{T}(s)\right|+\left|y-\gamma_{R}(s)\right|-\left(\left|x-\gamma_{T}(s)\right|+\left|x-\gamma_{R}(s)\right|\right)\right) . \tag{11}
\end{equation*}
$$

Proposition 5.1. The wavefront set of the kernel $K$ of $F^{*} F$ satisfies,

$$
W F(K)^{\prime} \subset \Delta \cup C_{1} \cup C_{2} \cup C_{3},
$$

where $\Delta$ is the diagonal in $T^{*} X \times T^{*} X$ and the Lagrangians $C_{i}$ for $i=1,2,3$ are the graphs of the following functions $\chi_{i}$ for $i=1,2,3$ on $T^{*} X$ :

$$
\chi_{1}(x, \xi)=\left(x_{1},-x_{2}, \xi_{1},-\xi_{2}\right), \quad \chi_{2}(x, \xi)=\left(-x_{1}, x_{2},-\xi_{1}, \xi_{2}\right) \quad \text { and } \quad \chi_{3}=\chi_{1} \circ \chi_{2}
$$

Furthermore we have:
(a) $\Delta$ and $C_{1}, \Delta$ and $C_{2}, C_{1}$ and $C_{3}, C_{2}$ and $C_{3}$ intersect cleanly in codimension 2 .
(b) $\Delta \cap C_{3}=C_{1} \cap C_{2}=\emptyset$.

Proof. In order to find the wavefront set of the kernel $K$, we consider the canonical relation $C^{t} \circ C$ of $F^{*} F: C^{t} \circ C=\left\{(x, \xi ; y, \eta) \mid(x, \xi ; s, t, \sigma, \tau) \in C^{t} ;(s, t, \sigma, \tau ; y, \eta) \in C\right\}$. We have that $(s, t, \sigma, \tau ; y, \eta) \in C$ implies

$$
\begin{gathered}
t=\sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+h^{2}}+\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+h^{2}}, \\
\sigma=\tau\left(\frac{y_{1}-s}{\sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+h^{2}}}-\frac{y_{1}+s}{\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+h^{2}}}\right),
\end{gathered}
$$

$$
\begin{align*}
\eta_{1} & =\tau\left(\frac{y_{1}-s}{\sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+h^{2}}}+\frac{y_{1}+s}{\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+h^{2}}}\right) \\
\eta_{2} & =\tau\left(\frac{y_{2}}{\sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+h^{2}}}+\frac{y_{2}}{\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+h^{2}}}\right) \tag{12}
\end{align*}
$$

and $(x, \xi ; s, t, \sigma, \tau) \in C^{t}$ implies

$$
\begin{gather*}
t=\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}+\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}, \\
\sigma=\tau\left(\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}-\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right), \\
\xi_{1}=\tau\left(\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}+\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right), \\
\xi_{2}=\tau\left(\frac{x_{2}}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}+\frac{x_{2}}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}}\right) . \tag{13}
\end{gather*}
$$

From the first two relations in (12) and (13), we have

$$
\begin{align*}
& \sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+h^{2}}+\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+h^{2}} \\
& \quad=\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}+\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}} \tag{14}
\end{align*}
$$

and

$$
\begin{align*}
& \frac{y_{1}-s}{\sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+h^{2}}}-\frac{y_{1}+s}{\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+h^{2}}} \\
& =\frac{x_{1}-s}{\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}}-\frac{x_{1}+s}{\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}} \tag{15}
\end{align*}
$$

We will use the prolate spheroidal coordinates to solve for $x$ and $y$. We let

$$
\begin{array}{cc}
x_{1}=s \cosh \rho \cos \phi, & y_{1}=s \cosh \rho^{\prime} \cos \phi^{\prime}, \\
x_{2}=s \sinh \rho \sin \phi \cos \theta, & y_{2}=s \sinh \rho^{\prime} \sin \phi^{\prime} \cos \theta^{\prime}, \\
x_{3}=h+s \sinh \rho \sin \phi \sin \theta, & y_{3}=h+s \sinh \rho^{\prime} \sin \phi^{\prime} \sin \theta^{\prime} \tag{16}
\end{array}
$$

with $\rho>0,0 \leqslant \phi \leqslant \pi$ and $0 \leqslant \theta<2 \pi$.
In this case $x_{3}=0$ and we use it to solve for $h$. Hence

$$
\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}=s^{2}(\cosh \rho-\cos \phi)^{2}
$$

and

$$
\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}=s^{2}(\cosh \rho+\cos \phi)^{2} .
$$

Noting that $s>0$ and $\cosh \rho \pm \cos \phi>0$, the first relation given by (14) in these coordinates becomes

$$
s(\cosh \rho-\cos \phi)+s(\cosh \rho+\cos \phi)=s\left(\cosh \rho^{\prime}-\cos \phi^{\prime}\right)+s\left(\cosh \rho^{\prime}+\cos \phi^{\prime}\right)
$$

from which we get

$$
\cosh \rho=\cosh \rho^{\prime} \quad \Rightarrow \quad \rho=\rho^{\prime}
$$

The second relation given by (15) becomes

$$
\frac{\cosh \rho \cos \phi-1}{\cosh \rho-\cos \phi}-\frac{\cosh \rho \cos \phi+1}{\cosh \rho+\cos \phi}=\frac{\cosh \rho \cos \phi^{\prime}-1}{\cosh \rho-\cos \phi^{\prime}}-\frac{\cosh \rho \cos \phi^{\prime}+1}{\cosh \rho+\cos \phi^{\prime}}
$$

After simplification we get

$$
\frac{\sin ^{2} \phi}{\cosh ^{2} \rho-\cos ^{2} \phi}=\frac{\sin ^{2} \phi^{\prime}}{\cosh ^{2} \rho-\cos ^{2} \phi^{\prime}}
$$

which implies

$$
\left(\cosh ^{2} \rho-1\right)\left(\sin ^{2} \phi-\sin ^{2} \phi^{\prime}\right)=0
$$

Thus $\sin \phi= \pm \sin \phi^{\prime} \Rightarrow \phi= \pm \phi^{\prime}, \pi \pm \phi^{\prime}$.
We remark that $\cos \theta= \pm \sqrt{1-\frac{h^{2}}{s^{2} \sinh ^{2} \rho \sin ^{2} \phi}}= \pm \cos \theta^{\prime}$ and note that $x_{3}=0$ implies that $\sin (\phi) \neq 0$, so that division by $\sin (\phi)$ is allowed here. We also remark that it is enough to consider $\cos \theta=\cos \theta^{\prime}$ as no additional relations are introduced by considering $\cos \theta=-\cos \theta^{\prime}$.

Now we go back to $x$ and $y$ coordinates.
If $\phi^{\prime}=\phi$ then $x_{1}=y_{1}, x_{2}=y_{2}, \xi_{i}=\eta_{i}$ for $i=1,2$. For these points, the composition, $C^{t} \circ C \subset \Delta=\{(x, \xi ; x, \xi)\}$.

If $\phi^{\prime}=-\phi$ then $x_{1}=y_{1},-x_{2}=y_{2}, \xi_{1}=\eta_{1},-\xi_{2}=\eta_{2}$. For these points, the composition, $C^{t} \circ C$ is a subset of $C_{1}=\left\{\left(x_{1}, x_{2}, \xi_{1}, \xi_{2} ; x_{1},-x_{2}, \xi_{1},-\xi_{2}\right)\right\}$ which is the graph of $\chi_{1}(x, \xi)=$ ( $x_{1},-x_{2}, \xi_{1},-\xi_{2}$ ). This in the base space represents the reflection about the $x_{1}$ axis.

If $\phi^{\prime}=\pi-\phi$ then $-x_{1}=y_{1}, x_{2}=y_{2},-\xi_{1}=\eta_{1}, \xi_{2}=\eta_{2}$. For these points, the composition $C^{t} \circ C$ is a subset of $C_{2}=\left\{\left(x_{1}, x_{2}, \xi_{1}, \xi_{2} ;-x_{1}, x_{2},-\xi_{1}, \xi_{2}\right)\right\}$ which is the graph of $\chi_{2}(x, \xi)=$ $\left(-x_{1}, x_{2},-\xi_{1}, \xi_{2}\right)$. This in the base space represents the reflection about the $x_{2}$ axis.

If $\phi^{\prime}=\pi+\phi$ then $-x_{1}=y_{1},-x_{2}=y_{2},-\xi_{1}=\eta_{1},-\xi_{2}=\eta_{2}$. For these points, $C^{t} \circ C$ is a subset of $C_{3}=\left\{\left(x_{1}, x_{2}, \xi_{1}, \xi_{2} ;-x_{1},-x_{2},-\xi_{1},-\xi_{2}\right)\right\}$ which is the graph of $\chi_{3}(x, \xi)=$ $\left(-x_{1},-x_{2},-\xi_{1},-\xi_{2}\right)$. This in the base space represents the reflection about the origin.

Notice that $\chi_{1} \circ \chi_{1}=I d, \chi_{2} \circ \chi_{2}=I d, \chi_{1} \circ \chi_{2}=\chi_{3}$.
So far we have obtained that $C^{t} \circ C \subset \Delta \cup C_{1} \cup C_{2} \cup C_{3}$.


Fig. 1. Support of the cut-off functions $\psi_{1}$ and $\psi_{2}$.

Next we consider the intersections of any two of these Lagrangians. We have:
$\Delta$ intersects $C_{1}$ cleanly in codimension $2, \Delta \cap C_{1}=\left\{(x, \xi ; y, \eta) \mid x_{2}=0=\xi_{2}\right\}$.
$\Delta$ intersects $C_{2}$ cleanly in codimension $2, \Delta \cap C_{2}=\left\{(x, \xi ; y, \eta) \mid x_{1}=0=\xi_{1}\right\}$.
$C_{1}$ intersects $C_{3}$ cleanly in codimension $2, C_{1} \cap C_{3}=\left\{(x, \xi ; y, \eta) \mid x_{1}=0=\xi_{1}\right\}$.
$C_{2}$ intersects $C_{3}$ cleanly in codimension $2, C_{2} \cap C_{3}=\left\{(x, \xi ; y, \eta) \mid x_{2}=0=\xi_{2}\right\}$.
$\Delta \cap C_{3}=\emptyset=C_{1} \cap C_{2}$.
Theorem 5.2. Let $F$ be as in (4) with order $m$. Then $F^{*} F$ can be decomposed as a sum of operators belonging in $I^{2 m, 0}\left(\Delta, C_{1}\right)+I^{2 m, 0}\left(\Delta, C_{2}\right)+I^{2 m, 0}\left(C_{1}, C_{3}\right)+I^{2 m, 0}\left(C_{2}, C_{3}\right)$.

Proof. Recall from Theorem 2.1, that the canonical relation of $F$ drops rank on the union of two sets, $\Sigma_{1}$ and $\Sigma_{2}$. Accordingly, we decompose $F$ into components such that the canonical relation of each component is either supported near a subset of the union of these two sets, one of these two sets or away from both these sets. More precisely, we let $\psi_{1}$ and $\psi_{2}$ be two infinitely differentiable functions defined as follows (refer Fig. 1):

$$
\psi_{1}(x)= \begin{cases}1, & \text { on }\left\{\left(x_{1}, x_{2}\right):\left|x_{2}\right|<\epsilon\right\} \\ 0, & \text { on }\left\{\left(x_{1}, x_{2}\right):\left|x_{2}\right|>2 \epsilon\right\}\end{cases}
$$

and

$$
\psi_{2}(x)= \begin{cases}1, & \text { on }\left\{\left(x_{1}, x_{2}\right):\left|x_{1}\right|<\epsilon\right\} \\ 0, & \text { on }\left\{\left(x_{1}, x_{2}\right):\left|x_{1}\right|>2 \epsilon\right\}\end{cases}
$$

Then we write $F=F_{0}+F_{1}+F_{2}+F_{3}$ where $F_{i}$ are given in terms of their kernels

$$
\begin{aligned}
K_{F_{0}}=\int e^{-i \varphi} a \psi_{1} \psi_{2} \mathrm{~d} \omega, & K_{F_{1}}=\int e^{-i \varphi} a \psi_{1}\left(1-\psi_{2}\right) \mathrm{d} \omega \\
K_{F_{2}}=\int e^{-i \varphi} a\left(1-\psi_{1}\right) \psi_{2} \mathrm{~d} \omega, & K_{F_{3}}=\int e^{-i \varphi} a\left(1-\psi_{1}\right)\left(1-\psi_{2}\right) \mathrm{d} \omega,
\end{aligned}
$$

where $\varphi$ is the phase function of $F$ in (4). Now we consider $F^{*} F$, which using the decomposition of $F$ as above can be written as

$$
\begin{align*}
F^{*} F= & F_{0}^{*} F+\left(F_{1}+F_{2}\right)^{*} F_{0}+F_{1}^{*} F_{1}+F_{2}^{*} F_{2}+F_{1}^{*} F_{2} \\
& +F_{2}^{*} F_{1}+F_{1}^{*} F_{3}+F_{2}^{*} F_{3}+F_{3}^{*} F . \tag{17}
\end{align*}
$$

The theorem now follows from Lemmas 5.3, 5.4 and Theorem 5.5 below, where we analyze each of the compositions above.

Lemma 5.3. $F_{0}, F_{1}^{*} F_{2}$ and $F_{2}^{*} F_{1}$ are smoothing operators.
Proof. We will only prove that $F_{0}$ and $F_{1}^{*} F_{2}$ are smoothing. The proof for $F_{2}^{*} F_{1}$ is similar to that of $F_{1}^{*} F_{2}$. Let $\tilde{\varphi}=\frac{1}{\omega} \varphi$, where $\varphi$ is the phase function in (4).

For $\delta=18 \epsilon^{2} / h$, we analyze $F_{0}$ according to the following cases:
(a) $\left\{(s, t): s>0,0<t<2 \sqrt{s^{2}+h^{2}}-\delta\right\}$.

For this case, we show that $K_{F_{0}}$ is smoothing. For, on $\left\{(s, t): s>0, t<2 \sqrt{s^{2}+h^{2}}-\delta\right\}$, $\tilde{\varphi}$ is bounded away from 0 and hence is a smooth function. Therefore for any $m \geqslant 0$

$$
\left(\frac{\mathrm{i}}{\tilde{\varphi}}\right)^{m} K_{F_{0}}(s, t, x)=\int \partial_{\omega}^{m}\left(e^{-\mathrm{i} \omega \tilde{\varphi}(s, t, x)}\right) \psi_{1}(x) \psi_{2}(x) a(s, t, x, \omega) \mathrm{d} \omega .
$$

Now by integration by parts, the order of the amplitude can be made smaller than any negative number. Therefore $K_{F_{0}}$ is smoothing.
(b) $\left\{(s, t): s>0,\left|t-2 \sqrt{s^{2}+h^{2}}\right| \leqslant \delta\right\}$.

For $(s, t)$ in this set, the kernel $K_{F_{0}}$ is identically 0 due to our choice of the function $g(s, t)$ in (3).
(c) $\left\{(s, t): s>0, t>2 \sqrt{s^{2}+h^{2}}+\delta\right\}$.

In this case, we have that depending on our choice of $x$, the kernel $K_{F_{0}}$ is either identically 0 or smoothing. For, if we consider $x$ in the complement of the set $(-2 \epsilon, 2 \epsilon)^{2}$, then due to the fact that $\operatorname{supp}\left(\psi_{1}(x) \psi_{2}(x)\right) \subset[-2 \epsilon, 2 \epsilon]^{2}$, we have that the kernel is identically 0 . Now
if we consider $x \in(-2 \epsilon, 2 \epsilon)^{2}$, then $\tilde{\varphi}$ is never vanishing. Then by an integration by parts argument as in Case (a) above, we have that $K_{F_{0}}$ is smoothing.

Now we consider $F_{2}^{*} F_{1}$. We have

$$
K_{F_{1}}(s, t, x)=\int e^{-\mathrm{i} \omega \tilde{\varphi}(s, t, x)} \psi_{1}(x)\left(1-\psi_{2}(x)\right) a(s, t, x, \omega) \mathrm{d} \omega
$$

and

$$
K_{F_{2}}^{*}(x, s, t)=\int e^{\mathrm{i} \omega \tilde{\varphi}(s, t, x)}\left(1-\psi_{1}(x)\right) \psi_{2}(x) \overline{a(s, t, x, \omega)} \mathrm{d} \omega .
$$

Due to the cut-off functions $\psi_{1}$ and $\psi_{2}$ in these kernels, we are only interested in those singularities lying above a small neighborhood of the rectangles with vertices $( \pm \epsilon, \pm \epsilon),( \pm \epsilon, \pm 2 \epsilon)$, $( \pm 2 \epsilon, \pm \epsilon),( \pm 2 \epsilon, \pm 2 \epsilon)$.

We have that $K_{F_{1}}$ is smoothing when $x$ values are restricted to a small neighborhood of these rectangles. For, as in the previous case, we consider the three cases: For Cases (a) and (c), the kernel $K_{F_{1}}$ is smoothing and the proof is identical as before. For Case (b), due to the choice of the function $g(s, t)$, the kernel $K_{F_{1}}=0$. Therefore $F_{2}^{*} F_{1}$ is smoothing.

Lemma 5.4. $F_{1}^{*} F_{3}, F_{2}^{*} F_{3}$ and $F_{3}^{*} F$ can be decomposed as a sum of operators belonging to the space $I^{2 m}(\Delta)+I^{2 m}\left(C_{1} \backslash \Delta\right)+I^{2 m}\left(C_{2} \backslash \Delta\right)+I^{2 m}\left(C_{3} \backslash\left(C_{1} \cup C_{2}\right)\right)$.

Proof. Each of these compositions is covered by the transverse intersection calculus. Below we will prove for the case of $F_{1}^{*} F_{3}$. For the other operators, the proofs are similar.

Let us decompose

$$
F_{3}=F_{3}^{1}+F_{3}^{2}+F_{3}^{3}+F_{3}^{4} \quad \text { and } \quad F_{1}^{*}=\left(F_{1}^{1}+F_{1}^{2}+F_{1}^{3}+F_{1}^{4}\right)^{*}
$$

where the superscripts in both these sums denote restriction of $F_{3}$ and $F_{1}$, respectively, to each of the four quadrants. Note that in the decomposition of $F_{1}^{*}$, we stay away from $\Sigma_{1}$ by introducing a microlocal cut-off. This is valid because the support of the canonical relation of $F_{3}$ stays away from $\Sigma_{1} \cup \Sigma_{2}$. Then we have

$$
\begin{array}{cl}
\left(F_{1}^{1}\right)^{*} F_{3}^{1} \in I^{2 m}(\Delta), \quad\left(F_{1}^{1}\right)^{*} F_{3}^{4} \in I^{2 m}\left(C_{1} \backslash \Delta\right), \\
\left(F_{1}^{1}\right)^{*} F_{3}^{2} \in I^{2 m}\left(C_{2} \backslash \Delta\right) \quad \text { and } & \left(F_{1}^{1}\right)^{*} F_{3}^{3} \in I^{2 m}\left(C_{3} \backslash\left(C_{1} \cup C_{2}\right)\right) .
\end{array}
$$

The other compositions can be considered similarly.
We are left with the analysis of the compositions $F_{1}^{*} F_{1}$ and $F_{2}^{*} F_{2}$. This is the content of the next theorem:

Theorem 5.5. Let $F_{1}$ and $F_{2}$ be as above. Then:
(a) $F_{1}^{*} F_{1} \in I^{2 m, 0}\left(\Delta, C_{1}\right)+I^{2 m, 0}\left(C_{2}, C_{3}\right)$.
(b) $F_{2}^{*} F_{2} \in I^{2 m, 0}\left(\Delta, C_{2}\right)+I^{2 m, 0}\left(C_{1}, C_{3}\right)$.

Proof. We consider $F_{1}^{*} F_{1}$. The proof for $F_{2}^{*} F_{2}$ is similar.
We decompose $F_{1}$ by introducing a smooth cut-off function $\psi_{3}(x)$ such that $\psi_{3}(x)=1$ for $x_{1}>\epsilon / 2$ and supported on the right-half plane $x_{1} \geqslant \epsilon / 4$. That is, we write $F_{1}$ as

$$
F_{1}=F_{1}^{+}+F_{1}^{-},
$$

where

$$
F_{1}^{+} V(s, t)=\int e^{-\mathrm{i} \varphi(s, t, x, \omega)} \psi_{1}(x)\left(1-\psi_{2}(x)\right) \psi_{3}(x) a(s, t, x, \omega) V(x) \mathrm{d} x
$$

and

$$
F_{1}^{-} V(s, t)=\int e^{-\mathrm{i} \varphi(s, t, x, \omega)} \psi_{1}(x)\left(1-\psi_{2}(x)\right)\left(1-\psi_{3}(x)\right) a(s, t, x, \omega) V(x) \mathrm{d} x
$$

Now

$$
\begin{equation*}
F_{1}^{*} F_{1}=\left(F_{1}^{+}\right)^{*} F_{1}^{+}+\left(F_{1}^{-}\right)^{*} F_{1}^{+}+\left(F_{1}^{+}\right)^{*} F_{1}^{-}+\left(F_{1}^{-}\right)^{*} F_{1}^{-} \tag{18}
\end{equation*}
$$

The canonical relation of $F_{1}^{+}$is a subset of (8) with the additional condition that $x_{1}>\epsilon$. Then we have that $W F\left(\left(F_{1}^{+}\right)^{*} F_{1}^{+}\right)^{\prime} \subset \Delta \cup C_{1}$. For, we already saw in Proposition 5.1 that $W F\left(F^{*} F\right) \subset \Delta \cup C_{1} \cup C_{2} \cup C_{3}$. In our case, imposing the additional restriction that $x_{1}>\epsilon$, the only contributions are in $\Delta$ and $C_{1}$. By a similar argument, we have that $W F\left(\left(F_{1}^{-}\right)^{*} F_{1}^{-}\right)^{\prime} \subset$ $\Delta \cup C_{1}$.

Now let us consider the compositions $\left(F_{1}^{-}\right)^{*} F_{1}^{+}$and $\left(F_{1}^{+}\right)^{*} F_{1}^{-}$. The wavefront sets of these operators are of the form $(x, \xi, y, \eta)$ such that $x_{1}$ and $y_{1}$ have opposite signs. We have already established in Proposition 5.1 that $\left|x_{i}\right|=\left|y_{i}\right|$ and $\left|\xi_{i}\right|=\left|\eta_{i}\right|$ for $i=1$, 2. Now with the additional restriction that $x_{1}$ and $y_{1}$ have opposite signs (and therefore $\xi_{1}$ and $\eta_{1}$ have different signs as well), we have contributions contained in only $C_{2}$ and $C_{3}$.

The Lagrangian pairs $\Delta, C_{1}$ and $C_{2}, C_{3}$ intersect cleanly. Therefore there is a well-defined $I^{p, l}$ class - which we will identify shortly - in which each of the summands in (18) lie.

We now show that $\left(F_{1}^{+}\right)^{*} F_{1}^{+},\left(F_{1}^{-}\right)^{*} F_{1}^{-} \in I^{2 m, 0}\left(\Delta, C_{1}\right)$ and that $\left(F_{1}^{-}\right)^{*} F_{1}^{+},\left(F_{1}^{+}\right)^{*} F_{1}^{-} \in$ $I^{2 m, 0}\left(C_{2}, C_{3}\right)$. We follow the ideas of [5], where the iterated regularity theorem of was used to prove an analogous result. The ideas of [5] were recently employed to prove a similar result for a common-offset geometry in [17]. The proof we give is similar to the one given in [17], but the phase function we work with is different.

We first consider the generator of the ideal of functions that vanish on $\Delta \cup C_{1}$ [5]

$$
\begin{array}{ll}
\tilde{p}_{1}=x_{1}-y_{1}, \quad \tilde{p}_{2}=x_{2}^{2}-y_{2}^{2}, \quad \tilde{p}_{3}=\xi_{1}-\eta_{1}, \quad \tilde{p}_{4}=\left(x_{2}+y_{2}\right)\left(\xi_{2}-\eta_{2}\right), \\
& \tilde{p}_{5}=\left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right), \quad \tilde{p}_{6}=\xi_{2}^{2}-\eta_{2}^{2}
\end{array}
$$

Let $p_{i}=q_{i} \tilde{p}_{i}$, for $1 \leqslant i \leqslant 6$, where $q_{1}, q_{2}$ are homogeneous of degree 1 in $(\xi, \eta), q_{3}, q_{4}$ and $q_{5}$ are homogeneous of degree 0 in $(\xi, \eta)$ and $q_{6}$ is homogeneous of degree -1 in $(\xi, \eta)$. Let $P_{i}$ be pseudodifferential operators with principal symbols $p_{i}$ for $1 \leqslant i \leqslant 6$.

We show in Appendix A that each $\tilde{p}_{i}$ can be expressed in the following forms:

$$
\begin{gather*}
\tilde{p}_{1}=\frac{f_{11}(x, y, s)}{\omega} \partial_{s} \Phi+f_{12}(x, y, s) \partial_{\omega} \Phi  \tag{19}\\
\tilde{p}_{2}=\frac{f_{21}(x, y, s)}{\omega} \partial_{s} \Phi+f_{22}(x, y, s) \partial_{\omega} \Phi  \tag{20}\\
\tilde{p}_{3}=f_{31}(x, y, s) \partial_{s} \Phi+\omega f_{32}(x, y, s) \partial_{\omega} \Phi  \tag{21}\\
\tilde{p}_{4}=f_{41}(x, y, s) \partial_{s} \Phi+\omega f_{42}(x, y, s) \partial_{\omega} \Phi  \tag{22}\\
\tilde{p}_{5}=f_{51}(x, y, s) \partial_{s} \Phi+\omega f_{52}(x, y, s) \partial_{\omega} \Phi  \tag{23}\\
\tilde{p}_{6}=\omega f_{61}(x, y, s) \partial_{s} \Phi+\omega^{2} f_{62}(x, y, s) \partial_{\omega} \Phi \tag{24}
\end{gather*}
$$

where $f_{i j}$ for $1 \leqslant i \leqslant 6$ and $j=1,2$ are smooth functions.
Now the rest of the proof is the same as in [5, Theorem 1.6]. We give it for completeness.
Let $K_{1}^{+}$be the kernel of $\left(F_{1}^{+}\right)^{*} F_{1}^{+}$. This is the kernel in (10), but with $\tilde{a}$ there replaced by $\psi_{1}(x)\left(1-\psi_{2}(x)\right) \psi_{3}(x) \psi_{1}(y)\left(1-\psi_{2}(y)\right) \psi_{3}(y) \tilde{a}(x, y, s, \omega)$. For simplicity, we rename this as $\tilde{a}$ again.

We then have that $\tilde{a} \in S^{2 m+1}$ and

$$
\begin{aligned}
P_{1} K_{1}^{+}(x, y)= & \int e^{\mathrm{i} \Phi(x, y, s, \omega)} \tilde{a}(x, y, s, \omega) q_{1}\left[\frac{f_{11}(x, y, s)}{\omega} \partial_{s} \Phi+f_{12}(x, y, s) \partial_{\omega} \Phi\right] \mathrm{d} s \mathrm{~d} \omega \\
= & \int \partial_{s}\left[e^{\mathrm{i} \Phi(x, y, s, \omega)}\right] \frac{q_{1}}{\mathrm{i} \omega} \tilde{a}(x, y, s, \omega) f_{11}(x, y, s) \mathrm{d} s \mathrm{~d} \omega \\
& +\int \partial_{\omega}\left[e^{\mathrm{i} \Phi(x, y, s, \omega)}\right] \frac{q_{1}}{\mathrm{i}} \tilde{a}(x, y, s, \omega) f_{12}(x, y, s) \mathrm{d} s \mathrm{~d} \omega
\end{aligned}
$$

By integration by parts

$$
\begin{aligned}
= & -\left\{\int e^{\mathrm{i} \Phi(x, y, s, \omega)} \partial_{s}\left[\frac{q_{1}}{\mathrm{i} \omega} \tilde{a}(x, y, s, \omega) f_{11}(x, y, s)\right] \mathrm{d} s \mathrm{~d} \omega\right. \\
& \left.+\int e^{\mathrm{i} \Phi(x, y, s, \omega)} \partial_{\omega}\left[\frac{q_{1}}{\mathrm{i}} \tilde{a}(x, y, s, \omega) f_{12}(x, y, s)\right] \mathrm{d} s \mathrm{~d} \omega\right\} .
\end{aligned}
$$

Note that $q_{1}$ is homogeneous of degree 1 in $\omega$, and $\tilde{a}$ is a symbol of order $2 m+1$, hence each amplitude term in the sum above is of order $2 m+1$.

Therefore by Proposition 3.7, we have that $P_{1} K_{1}^{+} \in H_{\mathrm{loc}}^{s_{0}}$ for some $s_{0}$.
A similar argument works for each of the other five pseudodifferential operators. Hence by Proposition 3.7, we have that $\left(F_{1}^{+}\right)^{*} F_{1}^{+} \in I^{p, l}\left(\Delta, C_{1}\right)$. Because $C$ is a local canonical graph away from $\Sigma$, the transverse intersection calculus applies for the composition $\left(F_{1}^{+}\right)^{*} F_{1}^{+}$away from $\Sigma$. Hence $\left(F_{1}^{+}\right)^{*} F_{1}^{+}$is of order $2 m$ on $\Delta \backslash C_{1}$ and $C_{1} \backslash \Sigma$. Since $\left(F_{1}^{+}\right)^{*} F_{1}^{+}$is of order $p+l$ on $\Delta \backslash \Sigma$ and is of order $p$ on $C_{1} \backslash \Sigma$, we have that $p=2 m$ and $l=0$. Therefore $\left(F_{1}^{+}\right)^{*} F_{1}^{+} \in$ $I^{2 m, 0}\left(\Delta, C_{1}\right)$. Similarly $\left(F_{1}^{-}\right)^{*} F_{1}^{-} \in I^{2 m, 0}\left(\Delta, C_{1}\right)$.

To show that $\left(F_{1}^{-}\right)^{*} F_{1}^{+},\left(F_{1}^{+}\right)^{*} F_{1}^{-} \in I^{2 m, 0}\left(C_{2}, C_{3}\right)$ we can use the iterated regularity result as above.

The generators of the ideal of functions that vanish on $C_{2} \cup C_{3}$ are:
$\tilde{r}_{1}=x_{1}+y_{1}, \tilde{r}_{2}=\xi_{1}+\eta_{1}$ and $\tilde{p}_{2}, \tilde{p}_{4}, \tilde{p}_{5}, \tilde{p}_{6}$ are the same as in (20), (22), (23), and (24) respectively. Four of the functions in the ideal are the same as in the proof above and we can find similar expressions for the first two.

However we will also give an alternate proof below.
Proposition 5.6. $\left(F_{1}^{-}\right)^{*} F_{1}^{+},\left(F_{1}^{+}\right)^{*} F_{1}^{-} \in I^{2 m, 0}\left(C_{2}, C_{3}\right)$.
Proof. We show for $\left(F_{1}^{-}\right)^{*} F_{1}^{+}$. The proof for the other case is similar. Consider the operator $R$ defined as follows:

$$
R V\left(x_{1}, x_{2}\right)=V\left(-x_{1}, x_{2}\right)
$$

This is a Fourier integral operator of order 0 with the canonical relation $C_{2}$. This is because,

$$
\begin{aligned}
R V\left(x_{1}, x_{2}\right) & =\int e^{\mathrm{i}(x-y) \cdot \xi} R_{2} V\left(y_{1}, y_{2}\right) \mathrm{d} y \mathrm{~d} \xi \\
& =\int e^{\mathrm{i}(x-y) \cdot \xi} V\left(-y_{1}, y_{2}\right) \mathrm{d} y \mathrm{~d} \xi \\
& =\int e^{\mathrm{i}\left[\left(x_{1}+y_{1}\right) \xi_{1}+\left(x_{2}-y_{2}\right) \xi_{2}\right]} V\left(y_{1}, y_{2}\right) \mathrm{d} y \mathrm{~d} \xi
\end{aligned}
$$

It is easy to check that canonical relation is $C_{2}$.
Now consider the operator $\widetilde{F}=F_{1}^{-} \circ R$. This is given by

$$
\widetilde{F} V(s, t)=\int e^{-\mathrm{i} \varphi(s, t, x, \omega)} b(s, t, x, \omega) V(x) \mathrm{d} x \mathrm{~d} \omega
$$

where

$$
b(s, t, x, \omega)=\left[\psi_{1}\left(1-\psi_{2}\right)\left(1-\psi_{3}\right)\right]\left(-x_{1}, x_{2}\right) a\left(s, t,-x_{1}, x_{2}, \omega\right)
$$

Note that $\left(1-\psi_{3}\right)\left(-x_{1}, x_{2}\right)=\psi_{3}\left(x_{1}, x_{2}\right)$ except in a small neighborhood of the origin. Since $\psi_{1}\left(1-\psi_{2}\right)$ is 0 in a neighborhood of the origin, and noting that we can arrange $\psi_{1}$ and $\psi_{2}$ to be symmetric with respect to $x_{1}$, we have

$$
\widetilde{F} V(s, t)=\int e^{-\mathrm{i} \varphi(s, t, x, \omega)}\left[\psi_{1}\left(1-\psi_{2}\right) \psi_{3}\right](x) a\left(s, t,-x_{1}, x_{2}, \omega\right) V(x) \mathrm{d} x \mathrm{~d} \omega .
$$

Now we have that $\widetilde{F}^{*} F_{1}^{+} \in I^{2 m, 0}\left(\Delta, C_{1}\right)$. In fact the kernel of this operator has the same form as in (10) and the same proof as in Theorem 5.5 applies. Next we use [15, Proposition 4.1] to show that $R^{*} \widetilde{F}^{*} F_{1}^{+} \in I^{2 m, 0}\left(C_{2}, C_{3}\right)$. It is straightforward to check that $C_{2} \circ \Lambda=C_{2}, C_{2} \circ C_{1}=C_{3}$ and $C_{2} \times \Delta$ (as well as $C_{2} \times C_{1}$ ) intersects $T^{*} X \times \Delta_{T^{*} X} \times T^{*} X$ transversally. Hence the hypotheses of $[15$, Proposition 4.1$]$ are verified and we conclude that $R^{*} \widetilde{F}^{*} F_{1}^{+} \in I^{2 m, 0}\left(C_{2}, C_{3}\right)$. Since $\widetilde{F}^{*}=$ $R^{*}\left(F_{1}^{-}\right)^{*}$ and $\left(R^{*}\right)^{2}=\mathrm{Id}$ we have $\left(F_{1}^{-}\right)^{*} F_{1}^{+} \in I^{2 m, 0}\left(C_{2}, C_{3}\right)$.

Since $I^{2 m}(\Delta) \in I^{2 m, 0}\left(\Delta, C_{1}\right), I^{2 m}\left(C_{i} \backslash \Delta\right) \in I^{2 m, 0}\left(\Delta, C_{i}\right)$ for $i=1,2$ and $I^{2 m}\left(C_{3} \backslash\right.$ $\left.\left(C_{1} \cup C_{2}\right)\right) \in I^{2 m, 0}\left(C_{1}, C_{3}\right)$, Theorem 5.2 follows using Lemmas 5.3, 5.4, Theorem 5.5 and Proposition 5.6.

Remark 5.7. Using the properties of the $I^{p, l}$ classes, $F^{*} F \in I^{2 m, 0}\left(\Delta, C_{1}\right)$ implies that $F^{*} F \in$ $I^{2 m}\left(\Delta \backslash C_{1}\right)$ and $F^{*} F \in I^{2 m}\left(C_{1} \backslash \Delta\right)$. This means that $F^{*} F$ has the same order on both $\Delta$ and $C_{1}$ which implies that the artifact $C_{1}$ has the same strength as the initial singularities given by $\Delta$. A similar statement can be applied to $C_{2}$ and $C_{3}$. Note that $C_{1}$ gives an artifact that is a reflection in the $x_{1}$ axis, $C_{2}$ gives an artifact that is a reflection in the $x_{2}$ axis, and $C_{3}$ gives an artifact that is a reflection in the origin.

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## Appendix A

Here we give the derivations of (19)-(24). We will work in the coordinate system defined in (16). We extend the phase function in (11) to $\mathbb{R}^{3}$ by letting

$$
\begin{aligned}
\widetilde{\Phi}= & \omega\left\{\sqrt{\left(y_{1}-s\right)^{2}+y_{2}^{2}+\left(y_{3}-h\right)^{2}}+\sqrt{\left(y_{1}+s\right)^{2}+y_{2}^{2}+\left(y_{3}-h\right)^{2}}\right. \\
& \left.-\left(\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+\left(x_{3}-h\right)^{2}}+\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+\left(x_{3}-h\right)^{2}}\right)\right\} .
\end{aligned}
$$

Then note that

$$
\left.\partial_{\omega} \widetilde{\Phi}\right|_{x_{3}=y_{3}=0}=\partial_{\omega} \Phi \quad \text { and }\left.\quad \partial_{S} \widetilde{\Phi}\right|_{x_{3}=y_{3}=0}=\partial_{s} \Phi
$$

## A.1. Expression for $x_{1}-y_{1}$

We obtain an expression for $x_{1}-y_{1}$ in the form

$$
A_{1}:=x_{1}-y_{1}=\frac{f_{11}(x, y, s)}{\omega} \partial_{s} \Phi+f_{12}(x, y, s) \partial_{\omega} \Phi,
$$

where $f_{11}$ and $f_{12}$ are smooth functions. In the coordinate system (16),

$$
\begin{gathered}
A_{1}=s\left(\cosh \rho \cos \phi-\cosh \rho^{\prime} \cos \phi^{\prime}\right), \\
\partial_{\omega} \tilde{\phi}=2 s\left(\cosh \rho^{\prime}-\cosh \rho\right), \\
\partial_{S} \widetilde{\Phi}=\omega\left\{\left(\frac{\cosh \rho^{\prime} \cos \phi^{\prime}+1}{\cosh \rho^{\prime}+\cos \phi^{\prime}}-\frac{\cosh \rho^{\prime} \cos \phi^{\prime}-1}{\cosh \rho^{\prime}-\cos \phi^{\prime}}\right)\right. \\
\left.-\left(\frac{\cosh \rho \cos \phi+1}{\cosh \rho+\cos \phi}-\frac{\cosh \rho \cos \phi-1}{\cosh \rho-\cos \phi}\right)\right\} \\
=2 \omega\left\{\frac{\cosh \rho^{\prime}-\cosh \rho^{\prime} \cos ^{2} \phi^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}}-\frac{\cosh \rho-\cosh \rho \cos ^{2} \phi}{\cosh ^{2} \rho-\cos ^{2} \phi}\right\} .
\end{gathered}
$$

After simplifying, we get,

$$
\begin{aligned}
= & 2 \omega\left\{\frac{\left(\cosh \rho-\cosh \rho^{\prime}\right)\left(\cosh \rho \cosh \rho^{\prime}-\cos ^{2} \phi \cos ^{2} \phi^{\prime}\right)}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)}\right. \\
& \left.+\frac{\left(\cosh \rho^{\prime} \cos ^{2} \phi-\cosh \rho \cos ^{2} \phi^{\prime}\right)\left(\cosh \rho \cosh \rho^{\prime}-1\right)}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)}\right\} .
\end{aligned}
$$

Now observing that $\cosh \rho^{\prime}-\cosh \rho=\frac{\partial_{\omega} \widetilde{\Phi}}{2 s}$ and adding and subtracting $\cosh \rho \cos ^{2} \phi$ to the second term on the right above, we have,

$$
\begin{aligned}
& \partial_{s} \widetilde{\Phi}+\frac{\omega}{s} \frac{\left(\cosh \rho \cosh \rho^{\prime}-\cos ^{2} \phi \cos ^{2} \phi^{\prime}\right)}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)} \partial_{\omega} \widetilde{\Phi} \\
&=2 \omega \frac{\left\{\left(\cosh \rho^{\prime}-\cosh \rho\right) \cos ^{2} \phi+\cosh \rho\left(\cos ^{2} \phi-\cos ^{2} \phi^{\prime}\right)\right\}\left(\cosh \rho \cosh \rho^{\prime}-1\right)}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)} .
\end{aligned}
$$

From this we get

$$
\begin{align*}
\cos \phi-\cos \phi^{\prime}= & \frac{\partial_{S} \widetilde{\Phi}\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)}{2 \omega \cosh \rho\left(\cosh \rho^{\prime} \cosh \rho-1\right)\left(\cos \phi+\cos \phi^{\prime}\right)} \\
& +\frac{\frac{\omega}{s} \partial_{\omega} \widetilde{\Phi}\left(\left(\cosh \rho \cosh \rho^{\prime}-\cos ^{2} \phi \cos ^{2} \phi^{\prime}\right)-\cos ^{2} \phi\left(\cosh \rho \cosh \rho^{\prime}-1\right)\right)}{2 \omega \cosh \rho\left(\cosh \rho^{\prime} \cosh \rho-1\right)\left(\cos \phi+\cos \phi^{\prime}\right)} . \tag{A.1}
\end{align*}
$$

Now note that

$$
\begin{aligned}
A_{1}= & \frac{s \partial_{s} \widetilde{\Phi}\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)}{2 \omega\left(\cosh \rho^{\prime} \cosh \rho-1\right)\left(\cos \phi+\cos \phi^{\prime}\right)}-\frac{\cos \phi^{\prime}}{2} \partial_{\omega} \widetilde{\Phi} \\
& +\frac{\omega \partial_{\omega} \widetilde{\Phi}\left(\left(\cosh \rho \cosh \rho^{\prime}-\cos ^{2} \phi \cos ^{2} \phi^{\prime}\right)-\cos ^{2} \phi\left(\cosh \rho \cosh \rho^{\prime}-1\right)\right)}{2 \omega\left(\cosh \rho^{\prime} \cosh \rho-1\right)\left(\cos \phi+\cos \phi^{\prime}\right)}
\end{aligned}
$$

Now letting $x_{3}=y_{3}=0$, we see that we have written $x_{1}-y_{1}$ as a combination in terms of $\partial_{\omega} \Phi$ and $\partial_{S} \Phi$ as follows:

$$
\begin{aligned}
= & \frac{s\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)}{2\left(\cosh \rho^{\prime} \cosh \rho-1\right)\left(\cos \phi+\cos \phi^{\prime}\right)} \frac{\partial_{s} \Phi}{\omega} \\
& +\left\{\frac{\left(\left(\cosh \rho \cosh \rho^{\prime}-\cos ^{2} \phi \cos ^{2} \phi^{\prime}\right)-\cos ^{2} \phi\left(\cosh \rho \cosh \rho^{\prime}-1\right)\right)}{2\left(\cosh \rho^{\prime} \cosh \rho-1\right)\left(\cos \phi+\cos \phi^{\prime}\right)}-\frac{\cos \phi^{\prime}}{2}\right\} \partial_{\omega} \Phi
\end{aligned}
$$

We can write the above expression in the Cartesian coordinate system. First, for simplicity, let

$$
\begin{aligned}
X_{1} & =\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}, \\
X_{2} & =\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}
\end{aligned}
$$

with $Y_{1}$ and $Y_{2}$ being similarly defined with $x$ replaced by $y$. Then we have

$$
\begin{aligned}
x_{1}-y_{1}= & \frac{s\left(\frac{Y_{1} Y_{2}}{s^{2}}\right)\left(\frac{X_{1} X_{2}}{s^{2}}\right)}{2\left(\left(\frac{Y_{1}+Y_{2}}{2 s}\right)\left(\frac{X_{1}+X_{2}}{2 s}\right)-1\right)\left(\frac{x_{1}}{\frac{X_{1}+X_{2}}{2}}+\frac{y_{1}}{\frac{Y_{1}+Y_{2}}{2}}\right) \frac{\partial_{s} \Phi}{\omega}} \\
& +\left\{\frac{\left(\frac{X_{1}+X_{2}}{2 s}\right)\left(\frac{Y_{1}+Y_{2}}{2 s}\right)-\frac{x_{1}^{2} y_{1}^{2}}{\left(\frac{X_{1}+X_{2}}{2}\right)^{2}\left(\frac{Y_{1}+Y_{2}}{2}\right)^{2}}-\left(\frac{x_{1}^{2}}{\left(\frac{X_{1}+X_{2}}{2}\right)^{2}}\left(\left(\frac{Y_{1}+Y_{2}}{2 s}\right)\left(\frac{X_{1}+X_{2}}{2 s}\right)-1\right)\right)}{2\left(\left(\frac{Y_{1}+Y_{2}}{2 s}\right)\left(\frac{X_{1}+X_{2}}{2 s}\right)-1\right)\left(\frac{X_{1}}{\frac{X_{1}+X_{2}}{2}}+\frac{y_{1}}{\frac{Y_{1}+Y_{2}}{2}}\right)}\right. \\
& \left.-\frac{y_{1}}{Y_{1}+Y_{2}}\right\} \partial_{\omega} \Phi .
\end{aligned}
$$

A.2. Expression for $x_{2}^{2}-y_{2}^{2}$

Now we write $x_{2}^{2}-y_{2}^{2}$ in the form

$$
\begin{equation*}
A_{2}:=x_{2}^{2}-y_{2}^{2}=\frac{f_{21}(x, y, s)}{\omega} \partial_{s} \Phi+f_{22}(x, y, s) \partial_{\omega} \Phi \tag{A.2}
\end{equation*}
$$

where $f_{21}$ and $f_{22}$ are smooth functions. $A_{2}$ in the coordinate system (16) is

$$
\begin{align*}
A_{2}= & s^{2}\left(\sinh ^{2} \rho \sin ^{2} \phi \cos ^{2} \theta-\sinh ^{2} \rho^{\prime} \sin ^{2} \phi^{\prime} \cos ^{2} \theta^{\prime}\right) \\
= & s^{2}\left(\sinh ^{2} \rho \sin ^{2} \phi-\sinh ^{2} \rho^{\prime} \sin ^{2} \phi^{\prime}\right)  \tag{A.3}\\
& +s^{2}\left(\sinh ^{2} \rho^{\prime} \sin ^{2} \phi^{\prime} \sin ^{2} \theta^{\prime}-\sinh ^{2} \rho \sin ^{2} \phi \sin ^{2} \theta\right) \tag{A.4}
\end{align*}
$$

For $x_{3}=y_{3}=0$, (A.4) is 0 . Therefore we focus only on the term (A.3), which we still denote as $A_{2}$, and obtain an expression of the form (A.2) for this term.

Using the formulas $\sinh ^{2} \rho=\cosh ^{2} \rho-1, \sin ^{2} \phi=1-\cos ^{2} \phi$, and simplifying, we have

$$
\begin{aligned}
A_{2}= & s^{2}\left(\left(\cosh ^{2} \rho-\cosh ^{2} \rho^{\prime}\right) \sin ^{2} \phi-\left(\cos ^{2} \phi-\cos ^{2} \phi^{\prime}\right) \sinh ^{2} \rho^{\prime}\right) \\
= & s^{2}\left(\left(\cosh \rho-\cosh \rho^{\prime}\right)\left(\cosh \rho+\cosh \rho^{\prime}\right)\right. \\
& \left.-\left(\cos \phi-\cos \phi^{\prime}\right)\left(\cos \phi+\cos \phi^{\prime}\right) \sinh ^{2} \rho^{\prime}\right)
\end{aligned}
$$

Recall that $\cosh \rho-\cos \rho^{\prime}=\frac{\partial_{\omega} \tilde{\phi}}{2 s}$ and using the expression for $\cos \phi-\cos \phi^{\prime}$ in (A.1), and setting $x_{3}=y_{3}=0$, we see that $x_{2}^{2}-y_{2}^{2}$ can be written in the form (A.2).

## A.3. Expression for $\xi_{1}-\eta_{1}$

Note that $\xi_{1}=\partial_{x_{1}} \Phi$ and $\eta_{1}=-\partial_{y_{1}} \Phi$ and so $A_{3}:=\xi_{1}-\eta_{1}=\partial_{x_{1}} \Phi+\partial_{y_{1}} \Phi$.
We have

$$
A_{3}=\omega\left\{\left(\frac{y_{1}-s}{\left|y-\gamma_{T}(s)\right|}+\frac{y_{1}+s}{\left|y-\gamma_{R}(s)\right|}\right)-\left(\frac{x_{1}-s}{\left|x-\gamma_{T}(s)\right|}+\frac{x_{1}+s}{\left|x-\gamma_{R}(s)\right|}\right)\right\} .
$$

In the coordinate system (16) this is

$$
=2 \omega\left(\frac{\sinh ^{2} \rho^{\prime} \cos \phi^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}}-\frac{\sinh ^{2} \rho \cos \phi}{\cosh ^{2} \rho-\cos ^{2} \phi}\right)
$$

Simplifying this, we get

$$
\begin{aligned}
= & 2 \omega\left\{\frac{\left(\cos \phi-\cos \phi^{\prime}\right)\left(-\sinh ^{2} \rho \cosh ^{2} \rho^{\prime}-\sinh ^{2} \rho^{\prime} \cos \phi \cos \phi^{\prime}\right)}{\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)}\right. \\
& \left.+\frac{\left(\cosh \rho-\cosh \rho^{\prime}\right)\left(\cosh \rho+\cosh \rho^{\prime}\right) \cos \phi^{\prime}\left(1-\cos \phi \cos \phi^{\prime}\right)}{\left(\cosh ^{2} \rho-\cos ^{2} \phi\right)\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \phi^{\prime}\right)}\right\} .
\end{aligned}
$$

Now noting that $\cosh \rho-\cosh \rho^{\prime}=\frac{\partial_{\omega} \widetilde{\Phi}}{2 s}$ and using the formula (A.1) for $\cos \phi-\cos \phi^{\prime}$ and setting $x_{3}=y_{3}=0$, we can write $A_{3}$ in the form (21).

## A.4. Expression for $\left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right)$

Using the coordinate system (16), we can write $A_{4}:=\left(x_{2}+y_{2}\right)\left(\xi_{2}-\eta_{2}\right)$ (up to a negative sign) as

$$
\begin{aligned}
& \left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right) \\
& \quad=\omega\left(x_{2}-y_{2}\right)\left(\frac{x_{2}}{\left|x-\gamma_{T}\right|}+\frac{x_{2}}{\left|x-\gamma_{R}\right|}+\frac{y_{2}}{\left|y-\gamma_{T}\right|}+\frac{y_{2}}{\left|y-\gamma_{R}\right|}\right) \\
& \quad=\frac{2 \omega}{s}\left(\frac{x_{2}^{2} \cosh \rho}{\cosh ^{2} \rho-\cos ^{2} \theta}-\frac{y^{2} \cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}+\frac{x_{2} y_{2} \cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}-\frac{x_{2} y_{2} \cosh \rho}{\cosh ^{2} \rho-\cos ^{2} \theta}\right)
\end{aligned}
$$

$$
\begin{aligned}
= & \frac{2 \omega}{s}\left(\frac{x_{2}^{2} \cosh \rho}{\cosh ^{2} \rho-\cos ^{2} \theta}-\frac{x_{2}^{2} \cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}+\left(x_{2}^{2}-y_{2}^{2}\right) \frac{\cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}\right. \\
& \left.+\frac{x_{2} y_{2} \cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}-\frac{x_{2} y_{2} \cosh \rho}{\cosh ^{2} \rho-\cos ^{2} \theta}\right) .
\end{aligned}
$$

Here we have added and subtracted $\frac{x_{2}^{2} \cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}$ in the previous equation. Simplifying this we get,

$$
\begin{aligned}
& \left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right) \\
& =\frac{2 \omega}{s}\left(( x _ { 2 } ^ { 2 } - x _ { 2 } y _ { 2 } ) \left[\frac{\left(\cosh \rho \cosh \rho^{\prime}+\cos ^{2} \theta\right)\left(\cosh \rho^{\prime}-\cosh \rho\right)}{\left(\cosh ^{2} \rho-\cos ^{2} \theta\right)\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)}\right.\right. \\
& \left.\left.\quad+\frac{\cosh \rho\left(\cos \theta+\cos \theta^{\prime}\right)\left(\cos \theta-\cos \theta^{\prime}\right)}{\left(\cosh ^{2} \rho-\cos ^{2} \theta\right)\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)}\right]+\left(x_{2}^{2}-y_{2}^{2}\right) \frac{\cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}}\right)
\end{aligned}
$$

Now note that $\cosh \rho^{\prime}-\cosh \rho=\frac{\partial_{\omega} \Phi}{2 s}$ and we already have expressions for $\cos \theta-\cos \theta^{\prime}$ (Eq. (A.1)) and for $x_{2}^{2}-y_{2}^{2}$ involving combinations of $\partial_{\omega} \Phi$ and $\partial_{s} \Phi$.

Hence we can write $\left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right)$ in the form of (22). Note that our calculation in this section shows that

$$
\begin{align*}
& \frac{\cosh \rho}{\cosh ^{2} \rho-\cos ^{2} \theta}-\frac{\cosh \rho^{\prime}}{\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}} \\
& =\frac{\left(\cosh \rho \cosh \rho^{\prime}+\cos ^{2} \theta\right)\left(\cosh \rho^{\prime}-\cosh \rho\right)}{\left(\cosh ^{2} \rho-\cos ^{2} \theta\right)\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)} \\
& \quad+\frac{\cosh \rho\left(\cos \theta+\cos \theta^{\prime}\right)\left(\cos \theta-\cos \theta^{\prime}\right)}{\left(\cosh ^{2} \rho-\cos ^{2} \theta\right)\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)} \tag{A.5}
\end{align*}
$$

This will be useful in the derivation of (24) in Appendix A. 6 below.

## A.5. Expression for $\left(x_{2}+y_{2}\right)\left(\xi_{2}-\eta_{2}\right)$

This is very similar to the derivation of the expression we obtained for $\left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right)$.

## A.6. Expression for $\xi_{2}^{2}-\eta_{2}^{2}$

We have

$$
\begin{aligned}
\xi_{2}^{2}-\eta_{2}^{2} & =\omega^{2}\left(\left(\frac{x_{2}}{\left|x-\gamma_{T}\right|}+\frac{x_{2}}{\left|x-\gamma_{R}\right|}\right)^{2}-\left(\frac{y_{2}}{\left|y-\gamma_{T}\right|}+\frac{y_{2}}{\left|y-\gamma_{R}\right|}\right)^{2}\right) \\
& =4 \omega^{2}\left(x_{2}^{2} \frac{\cosh ^{2} \rho}{\left(\cosh ^{2} \rho-\cos ^{2} \theta\right)^{2}}-y_{2}^{2} \frac{\cosh ^{2} \rho^{\prime}}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)^{2}}\right)
\end{aligned}
$$

$$
\begin{aligned}
= & 4 \omega^{2}\left\{x_{2}^{2}\left(\frac{\cosh ^{2} \rho}{\left(\cosh ^{2} \rho-\cos ^{2} \theta\right)^{2}}-\frac{\cosh ^{2} \rho^{\prime}}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)^{2}}\right)\right. \\
& \left.+\left(x_{2}^{2}-y_{2}^{2}\right) \frac{\cosh ^{2} \rho^{\prime}}{\left(\cosh ^{2} \rho^{\prime}-\cos ^{2} \theta^{\prime}\right)^{2}}\right\} .
\end{aligned}
$$

Now using the computations for $x_{2}^{2}-y_{2}^{2}$ and $\left(x_{2}-y_{2}\right)\left(\xi_{2}+\eta_{2}\right)$, in particular (A.5), we can write $\xi_{2}^{2}-\eta_{2}^{2}$ in the form

$$
\xi_{2}^{2}-\eta_{2}^{2}=\omega f_{61}(x, y, s) \partial_{s} \Phi+\omega^{2} f_{62}(x, y, s) \partial_{\omega} \Phi
$$

for smooth functions $f_{61}, f_{62}$.

## Appendix B

Here we explain the reason for setting $g(s, t)=0$ for $\left|t-2 \sqrt{s^{2}+h^{2}}\right|<20 \epsilon^{2} / h$ in (3).
In the proof of Theorem 5.2 - more precisely Lemma 5.3 - recall that we consider four squares with vertices $( \pm \epsilon, \pm \epsilon),( \pm \epsilon, \pm 2 \epsilon),( \pm 2 \epsilon, \pm \epsilon),( \pm 2 \epsilon, \pm 2 \epsilon)$. The motivation to choose $g=0$ as above comes from the fact that we want the amplitude term $a$ of $F$ to be 0 for those ( $s, t$ ) such that the ellipse defined by it is contained in a small neighborhood containing these squares.

One way to find this is as follows:
Given $(s, t)$, the ellipse $\sqrt{\left(x_{1}-s\right)^{2}+x_{2}^{2}+h^{2}}+\sqrt{\left(x_{1}+s\right)^{2}+x_{2}^{2}+h^{2}}=t$ can be written in the form

$$
\left(4 t^{2}-16 s^{2}\right) x_{1}^{2}+4 t^{2} x_{2}^{2}=t^{4}-4 t^{2}\left(s^{2}+h^{2}\right)
$$

Note that for this ellipse, the length of the semi-minor axis is always smaller that the length of the semi-major axis. The point $(2 \epsilon, 2 \epsilon)$ is $2 \sqrt{2} \epsilon$ away from the origin. Therefore let us choose a $t$ for which the ellipse passes through the point $(0,3 \epsilon)$. The time $t$ is such that

$$
t^{2}-4\left(s^{2}+h^{2}\right)=36 \epsilon^{2}
$$

Hence

$$
t-2 \sqrt{s^{2}+h^{2}}=36 \epsilon^{2} /\left(t+2 \sqrt{s^{2}+h^{2}}\right)
$$

Since $t>0$ and $s>0$, we have

$$
t-2 \sqrt{s^{2}+h^{2}}<18 \epsilon^{2} / h
$$

This explains the factor 18 in Lemma 5.3. Now choosing 20 (any number bigger than 18 would do) explains our choice of the constant in (3).

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